Instruction Manual

Micro Control X

Model: PXF5/9

Fuji Electric Co., Ltd.

INP-TN2PXF5/9a-E

Grobal Sales Section

Fuii Electric

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Thank you for purchasing the Fuji module type temperature controller.

Once you have confirmed that this is the product you ordered, please use it in accordance with the following

For detailed information on operating this equipment, please refer to the separate user's manual In addition, please keep this instruction manual within easy reach of the actual person using this equipment

CAUTION

The contents of this manual are subject to change without notice. This manual is complied with possible care for the purpose of accuracy, however,

Fuji Electric shall not be held liable for any damages, including indirect damage, caused by typographical errors,

manual

Document

Data sheet

absence of information or use of information in this manual.

Confirming Specifications and Accessories

Before using the product, confirm that it matches the type ordered. (For model code, please refer to pages 22 - 23.)

Confirm that all of the following accessories are included

Temperature Controller	1 unit
Instruction Manual	1 copy
Panel mounting adapter	2 pc
Waterproof packing	1 pc

Micro Controller (Model: PXF) Communication Functions Manual (MODBUS)	INP-TN5A2227-E
The latest manuals can also be	e downloaded at the

Related Information

Refer to the following reference materials

for details about the items described in this

Reference No.

EDS11-179 EDS11-180

INP-TN5A2400-E

following URL http://www.fujielectric.com/products/instruments/

Micro Controller (Model: PXF) Operation Manual

Option		
Name	Quantity	Order No.
Terminal cover*	1 pc	ZZPPXF1-B100
PC loader communication cable	1 cable	ZZP*TQ501923C3
Shunt resistor (250Ω ± 0.1%)	1 pc	ZZPPXR1-A190

*For PXF9, two terminal covers are necessary for one unit.

Please Read First (Safety Warnings)

Please read this section thoroughly before using and observe the mentioned safety warnings fully. Safety warnings are categorized as "Warning" or "Caution". Failure to follow the instructions may result in a safety hazard.

\land Warning	mishandling may lead to minor or serious personal injury, fire, and/or property damage.
▲ Caution	Mishandling may cause injury to the user or property damage.

If the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired

🕂 Warning

1-1. Limitations in Use

This product is a temperature controller which was developed, designed and manufactured on the premise that it would be used for general machinery.

In particular, if this product is to be used for applications that require the utmost safety as described below, please take into consideration of the safety of the entire system and the machine by adopting such means as a fail-safe design, a redundancy design as well as the conducting of periodical inspections.

- · Safety devices for the purpose of protecting the human body
- Direct control of transportation equipment
- Airplanes
- Space equipment

 Atomic equipment, etc. Please do not use this product for applications which directly involve human lives. 1-2. Installation and Wiring

This equipment is intended to be used under the following conditions.

Ambient temperature	-10 °C to 50 °C	-10 °C to 50 °C			
Ambient humidity	90% RH or below (with no condens	90% RH or below (with no condensation)			
Overvoltage category	11	by IEC 61010 1			
Pollution degree	2	by IEC 81010-1			
Recommended fuse	250VAC, 0.1A T(Time-Lag) for 100 400V DC/400V AC, 1A T(Time-Lag	/AC, 0.1A T(Time-Lag) for 100 to 240V AC Power supply, / DC/400V AC, 1A T(Time-Lag) for 24V DC/24V AC Power supply			
Usage environment	Indoor use				

- If accessible Safety Extra Low Voltage (SELV) circuits are to be connected to Signal input terminal, SSR Drive output terminal, Current output terminal or Communication (RS485) terminal, ensure to provide a basic insulation between the SELV circuits and these terminals (For example, use transformer which has a basic insulation or higher degree of insulation). The basic insulation requires a clearance at least 1.5 mm and a creepage of at least 3.0 mm. If such insulation is not provided, the UL61010 and EN61010 safety compliance may become invalid.
- For 24V DC/AC power supply model, if the equipment is connected to the Safety Extra Low Voltage (SELV) circuit, a basic insulation must be provided between the SELV circuit and the power input terminals. Otherwise, the power input terminals must be connect to Extra Low Voltage (ELV) circuit so as to prevent the electric shock.
- For CT input, use Current Transfer which has specification as shown below in order to prevent the electric shock and spread of fire.

1) Over Voltage Category	I
2) Pollution Degree	2
3) Required level of Insulating	BASIC INSULATION, SUPPLYMENTARY INSULATION, or REINFORCED INSULATION
4) Maximum Voltage line to neutral	300Vac rms or 300Vdc

About safety standard

Please observe the following instructions to meet the requirements of safety standard. Failure to observe these instructions violates safety standards. (This product is not a safety equipment.)

- Install a recommended fuse, which is specified in the instruction manual, between the external main power (mains circuit) and this equipment.
 If accessible Safety Extra Low Voltage (SELV) circuits are to be connected to Signal input terminal, SSR Drive output terminal, Current output terminal or Communication (RS485) terminal, ensure to provide a basic insulation between the SELV circuits and these terminals (For example, use transformer which has a basic insulation to righter degree of insulation). The basic insulation or equires a clearance at least 1.5 mm and a creepage of at least 3.0 mm. If such insulation is not provided, the UL61010 and EN61010 safety compliance may become invalid Compliance are easily of min. If such insulation is not provided, the UL61010 and EN61010 safety
 compliance may become invalid.
 Whole this equipment must be mounted in an enclosure in order to prevent the electric shock and spread
 of fire.
- Be sure to install an appropriate external protective circuit to prevent excessive temperature rise etc.
 When performing wiring work, be sure to turn the power off and to wear protection gloves or safety glasses
- The performing winning work, be sure to turn the power off and to wear protection gloves or safety glasses, to prevent an electric shock.
 Set proper parameter input signals which correspond to each input to be connected. Be careful not to confuse voltage input with current input, or vice versa.
 Do not use this equipment for the measurement of circuits which falls under measurement categories II, III, or IV.
- or IV. Do not use this equipment for measurement of signals to which a voltage over 30 VRMS or over 60 V DC is
- applied. If there is a risk that anyone may come into contact with the terminal while the instrument is being energized, attach the terminal cover (optional) to prevent an electric shock. Before removing a terminal cover, turn off all the power.
- Note that the insulation class for this equipment is as follows. Before installing, please confirm that the insulation class for equipment meets usage requirements Basic insulation (1500 V AC) Functional insulation (500 V AC) ----- No insulation Internal circuit Internal circuit Power supply (100 to 240V AC) er supply (24V DC/24V AC) Process value input Process value input Control output 1 (relay contact) Control output 1 (relay contact) Remote SV input Remote SV input Motorized valve OPEN output Motorized valve OPEN output CT input CT input Valve position feedback (PFB) input Control output 1 (SSR drive, current, voltage) Introl output 2 (SSR drive, current voltage) or Transfer output CT input CT input Valve position feedback (PFB) input Control output 1 (SSR drive, current, voltage) introl output 2 (SSR drive, current voltage) or Transfer output Control output 2 (relay contact) Control output 2 (relay contact) or Motorized valve CLOSE output or Motorized valve CLOSE output Alarm output 4 and 5 (relav contact) Alarm output 4 and 5 (relay contact) Alarm output 1 (relay contact) Alarm output (relay contact

Digital input 1 to 5

Communication (RS-485)

Alarm output

1 to 3 (relay contact

(2)

Alarm output 2 (relay contact) (1)

): When the 9th code is "J" AL 1 and 2: independent common

Alarm output

1 to 3 (relay contact)

(2)

(2): When the 9th code is other than "J" AL 1 to 3: shared common

Digital input 1 to 5

Communication (RS-485)

- A power switch or a circuit breaker should be installed within the power supply facility.
 A power switch or a circuit breaker should be properly installed within easy reach of an operator. · A power switch or a circuit breaker should be identified as the one for this product.
- Electrical wiring must be made by the qualified personnel only and in accordance with your local and national standards.

Alarm output

(i)

- · For power supply wiring, use wire equal to 600V vinyl insulated wire or above
- To prevent damage and failure of the equipment, provide the rated power voltage.
 To prevent shock and equipment failure, do not turn the power ON until all wiring is complete.
- Before turning on power, confirm that clearance space has been secured to prevent shock or fire.
 Do not touch the terminal while the machine is on. Doing so risks shock or equipment errors.
- Never disassemble, convert, modify or repair this equipment. Doing so risks abnormal operation,
- shock or fire.
- If any failure occurs, please contact the manufacturer and return the product.
 Output relay is the part has a limited life. When output relay contact comes to the end of its life, it
- might remain on-state, or off-state. For safety, use a protective circuit outside. The factory default setting of this equipment is as follows. Change the setting as necessary so as the equipment to meet your application. Please note that the improper settings may result in overheat or unexpected damage.

For the details of operation, refer to the separate volume, "Operation Manual (INP-TN5A2400-E)". Control output 1: heating control

- Control output 1 (optional): cooling control Alarm output 1 (optional): no alarm Alarm output 2 (optional): no alarm Alarm output 2 (optional): no alarm

- Alarm output 4 (optional): no alarm Alarm output 5 (optional): no alarm
- Symbols on the instrument

A : Read this instruction manual thoroughly before using the product, and usethe product safely.

1-3. Maintenance

- When installing or removing the equipment, turn the power OFF. Otherwise, shock, operational errors or failures may be caused.
- Periodic maintenance is recommended for continuous and safe use of this equipment
- Some parts installed on this equipment have a limited life and/or may deteriorate with age
- The warranty period for this unit (including accessories) is three years after the date of manufacture, if the product is used properly.

/ ↑ Caution

Cautions when Installing

Please avoid installing in the following locations

- Locations in which the ambient temperature falls outside the range of -10 to 50°C when equipment is in use. (If the power supply is 200V AC, the recommended maximum ambient temperature is 45°C)
- Locations with rapid temperature changes, leading to dew condensation
- Locations with corrosive gases (especially sulfide gas, ammonia, etc.) or flammable gases.
 Locations with vibration or shock directly. (Vibration and shock may cause output relay malfunction.)
- Locations in contact with water, oil, chemicals, steam or hot water.
- (If the equipment gets wet, there is a risk of electric shock or fire, so have it inspected by Fuji distributor) Locations with high concentrations of atmospheric dust, salt or iron particles.
- Locations with large inductive interference, resulting in static electricity, magnetic fields or noise
 Locations in direct sunlight.
- Locations that build up heat from radiant heat sources, etc.

Recommended site conditions A place where the ambient humidity during operation is between 45 to 85%RH.

About EMC standard

This equipment is a class A, for industrial locations, equipment. Do not use this equipment in domestic establishment, such as residential areas, or it may cause radio interference. If you use this equipment in domestic locations, take adequate measures on the outside of the equipment to reduce radio interference. Under the requirement of EMC standard, the maximum length of external cable including a sensor to be connected to this equipment is 30 m. Do not connect the sensor longer than 30 m.

2-2. Cautions when Attaching to the Panels

- Please attach the PXF5/PXF9 with the included fixtures (2 pieces) to the top and bottom, and tighten with a screwdriver.
- The clamp torque is approximately 0.15 N/m (1.5 kg/cm) It is designed such that overtightening will cause left/right cracking to the central area of the Fixtures and hence reduce the torque.
- Cracking to the central area will not cause any problems in terms of usability of the equipment (However, do exercise caution in not applying too much torque because the casing is made of
- plastic.) The front of this equipment is waterproof in compliance with NEMA-4X standards (IP66- equivalent) To effect waterproof, the included packing is shall be attached between the controller and the panel according to the guidelines below. (Incorrect attachment may cause the equipment to lose its waterproof capabilities.)
- (1) As shown in Fig. 1, insert to the panel after attaching the packing to the equipment case
- (2) As shown in Fig. 2, tighten the fixture screws so that no gaps can remain between the equipment face, the packing and the panels. Once finished, confirm that there are no changes in shape
- such as displaced or improperly-fitted packing, etc. as shown in Fig. 3. If the panel does not have enough strength, gaps may develop between the packing and the panel to lose waterproofing capabilities



Attachment on vertical surface (Horizontal attachment)

Caution

In order to aid heat dissipation, do not block the sides of the equipment.
Do not block the air vents on the top and bottom of the case.

2-3. Cautions for Wiring

- · For thermocouple input, use the designated compensation lead; for resistance bulb input, use wires
- with small lead wire resistance and without any resistance difference among the three wires. To avoid noise conductor effects, input signal wires should be separated from electric power lines or
- load lines • Input signal wire and output signal wire should be separated each other. And both should be shield
- wire • If there is a lot of noise from the power source, adding an insulation transducer and using a noise filter is recommended

(Example: ZMB22R5-11, noise filter, Manufacturer: TDK) Always attach a noise filter to a panel that is grounded securely, and keep the wiring between the noise filter output side and the measuring equipment power terminal wiring to a minimum length. Please do not attach fuses and switches, etc. to the noise filter output wiring; otherwise the filter's

- effectiveness will be decreased. • Twisting the power wires is effective when connecting the wires. (The shorter the pitch of the twist, the more effective the connection is against noise.)
- Operation preparation time is required for the contact output when power is turned on. If using it as
 a signal to an external interlock circuit, please couple it with a delayed relay.
 (Example)
- (Example)
- Concerning the output relay, connecting the maximum rated load will shorten the product's life; so please attach an auxiliary relay. If the output operation frequency is high, selecting a SSR/SSC drive output type is recommended. [Proportionate cycles] Relay output: 30 seconds or more, SSR/SSC drive output: 1 second or more
- If you selected the version with the heater break alarm, use a common power line for the heater and the controller.
- When inductive loads such as magnetic opening/closing equipment, etc. as relay output equipment are connected, use of a surge absorber is recommended in order to protect the contacts against opening/closing surges and to ensure long-term use.

Recommended specification for the surge absorber

Voltage	Nominal varistor voltage
100 V	240 V
200 V	470 V

. If the input wiring breaks, the display will read "UUUU". When replacing the sensor, always turn the power OFF.

2-5. Others

· Please do not wipe the equipment with organic solvents such as alcohol or benzene, etc. If wiping is necessary, use a neutral cleaning agent. • Do not use mobile phones near this equipment (within 50 cm). Otherwise a malfunction may result.

The alarm function does not work properly when an error takes place unless the settings are made correctly. Always verify its setting before operation.

- Trouble may occur if the equipment is used near a radio. TV, or wireless device
- This equipment should be treated as an industrial waste when it is disposed of.

2-4. Key Operation Cautions/Error Operations

For Proper Usage



Attachment position: between the relay control output contacts.

29 2

31

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Installation and Mounting 3.

3-1. External/Panel Cut Dimensions





* When using the parameter loader with PXF being mounted on a panel: t (panel thickness) 1 \leq t \leq 4



Rear view

Terminal block is not attached to unused terminals (from terminal 13 to 24) depending on model.

Installing multiple controllers



Caution

Close mounting in horizontal direction (n units) Horizontally close mounting does not meet

NEMA4X/IP66 (front waterproof specification), because packing cannot be used in this mounting



- Panel cut dimensions should also meet the above dimensions after the panel is coated. Cautions when Close Fit Mounting: When the power supply is AC 200V, keep the maximum ambient temperature at 45°C. If any equipment or walls which have a depth of 70 mm exist around this instrument, keep a clearance of at least: 30 mm on the both sides, 50 mm below, 30 mm above.
- Start by wiring from the left-hand terminals (terminals 1 to 12).
 Use a screw that is the right size on terminals and tighten them with a torque of about 0.8
- Do not attach anything to unused terminals. (Do not use relay terminals.)

PXF9



* When using the parameter loader with PXF being mounted on a panel: t (panel thickness) 1 \leq t \leq 4



Rear view

Terminal block is not attached to unused terminals (from terminal 13 to 24) depending on model.

Installing multiple controllers



4-1. Terminal Connection Diagram (Syandard type)

Standard type Relay output (SPST) Relay output (SPDT) SSR Current Voltage OUT -m - NO L. €___сом Control OUT т_____сом -ф<u>-</u>сом output 1 - COM 6 - NC -③ Re-transmission Re-transmission output (current) output (voltage) Relay output (SPST) SSR Current Voltage Control output 2 (4 _____ сом OUT2 Option RS-485 (1) (13) 25 2 (14) 26 25 RS485 27) 3 (15) @_ (16) 28 (4) 5 17 29 6 (18) 30 Digital input 1 (19 31 8 20 32 ିମ୍ଭିରୁ DI1 ଅନ୍ତି DI-COM 9 21 33 (10) 22 34 @**_**' DI2 (11) 23 35 112 2 36 CT input (31 Alarm output ً DCT1 2 points (independent common) 3 points 1 or 2 points 3 AL1 --6--> AL1--6---AL1-AL1 COM AL2 $\hat{7}$ Non-C \bigcirc AL2 AL3 AL2 Process value input AL2 COM -СОМ COM 9 9 (Note 1) Universal input Note 1: Power supplies for AL1 and AL2 must be of the same type, 34 A either AC or DC. 34 ₫.BÌ 35 35 (35 ۲ <u>_</u>___ БВ Power supply Option 36 36 24VAC/24VDC 100-240VAC Digital output Thermocouple RTD Current Voltage input input 1 11 vr-∰ AL4 ę q -12 -12 H COM 50/60Hz 50/60Hz Digital input _____ DI3 ⁽¹³ + _____ DI-COM ⁽¹³ + _____ DI-COM ⁽¹³ + _____ DI-COM ^{ال} DI5 0 Remote SV input

Control output 1

- Relay output (SPST) 250 V AC, 3 A (resistive load)
 Relay output (SPDT)
- 250 V AC, 5 A (resistive load) SSR output 12 V DC, 20 mA
- Current output
- 4 to 20 mA/0 to 20 mA (up to 500 Ω)
- Voltage output 0 to 5 V/1 to 5 V/0 to 10 V/2 to 10 V (MIN. 10 k $\Omega)$

Control output 2

- Relay output 250 V AC, 3 A (resistive load)
 SSR output
- 12 V DC, 20 mA Current output
- 4 to 20 mA/0 to 20 mA (up to 500 Ω)
- Voltage output 0 to 5 V/1 to 5 V/0 to 10 V/2 to 10 V (MIN. 10 kΩ)

₩ ∰____RSV1

Alarm output 1 to 5

- Relay output 250 V DC, 1 A (resistive load)

Note) If you use PXF as a substitute for PXR or PXG which was used with SSR output, be careful about the contlol voltage of SSR, for it is different among PXR, PXG, and PXF.

Madal	Output voltage range [V]			
woder	min	max		
PXF	10.7	13.2		
PXR	17.0	25.0		
PXG	18.0	24.0		

Note) It is not necessary to make a mistake in the wiring for themeasurements input terminal. There is a possibility that theinput circuit breaks when it makes a mistake in wiring.



Alarm output 1 to 3 • Relay output 250 V DC, 1 A (resistive load)

Display and Operations 5.

5-1. Part names and functions

Operation parts



Display

PXF5



PXF9



USER Key

Press this key once in PV/SV display to switch between SV display and MV display. Press and hold this key in PV/SV display to start the assigned function. Press this key once in operation control mode, channel-selection mode, or setup mode to return to PV/SV display.

SEL key Press this key once in operation mode to move to operation control mode.

Press and hold this key in operation mode to move to channel selection mode. Press this key once in channel selection mode to move to setup mode. Press and hold this key in setup mode to move to channel selection mode. Press this key once in parameter selection submode of setup mode to enter parameter editing

submode.

Press this key once in parameter editing submode to save the change and return to parameter selection submode.

< key

Use this key to select the digit when changing values.

∧∨keys

Use this key to change SV value when in PV/SV screen. Press this key in operation control mode, channel selection mode, or setup mode, to change parameters to be displayed. Use this key to edit parameter when in parameter setting submode.

USER+A key Press and hold this key in PV/SV display to start the assigned function. (The factory set function for this key is switching between RUN and standby.)

USER+∨ key

Press and hold this key in PV/SV display to start the assigned function. (The factory set function for this key is switching between start/stop of auto-tuning.)

(1) Process value (PV)

Indicates process value. Shows parameter name when in parameter setting.

(2) Set point (SV) Shows set point. Shows parameter set value when in parameter setting.

(3) Screen No. Shows screen No, when in parameter setting

(4) OUT 1 indicator Lights during control output 1 is ON.

(5) OUT 2 indicator Lights during control output 2 is ON.

(6) EV 1, EV 2, EV 3 indicators Lights during digital output 1 to 3 are ON.

(7) STBY indicator Lights during standby

(8) MANU indicator

Lights during manual mode.

(9) Lock indicator Lights during key lock.

(10) No. indicator Lights during indicating screen No.

(11) RUN/HOLD/END indicators Lights during ramp/soak operation

(12) AT indicator Lights during auto tuning.

(13) MV indicator Lights during MV is indicated on SV display.

(14) TM indicator Lights during the time is indicated on SV display.

(15) RMN indicator Lights during remaining time is indicated on SV display.

(16) °C/°F indicator

Shows the temperature unit under use.

(17) A/%/kW/h indicator

Shows the unit under use for the values indicated on SV display. (18) Bar graph display

Displays a bar graph of control output (MV) during operation.

5-2. Basic Operations

The below figure illustrates the mode transition and the key operations.



Operation mode

In this mode the normal operation is performed. The process value (PV) and the set value (SV) are displayed. The device starts in this mode when you turn on the power. You can change the set value (SV) in this mode. You can check the output value (MV) and the amount of electric ower by switchin the screen.

Operation control mode

In this mode you can put the device to standby or change the alarm set value.

Channel selection mode

In this mode you can select the parameter channel to be displayed.

Setup mode

In this mode you can setup each parameter. This mode includes the parameter selection submode and the parameter editing submode, which can be switched by SEL key. In the parameter selection submode, you can switch between parameters by using AV keys. In the parameter editing submode, you can change parameter values by using AV keys.

5-3. Changing values on operation screen

Changing SV (set values)



Change the display to PV/SV display (shown when you turn on the power and the SV lamp is lit).



3

Change the SV with the $\bigotimes \bigotimes$ keys.

Press the (st) key to save the values. (The value will be automatically saved after 3 seconds even if a key is not pressed.) Changing MV (control output values)

Switch to manual mode.

Change the display to PV/MV display (MAN/AT/SELF lamp is lit).



2

(Pressing the $\ensuremath{\underbrace{\text{SEL}}}$ key in manual mode toggles between PV/SV display and PV/MV display.)

 $3 \quad \text{Change the MV with the } \bigcirc \bigodot \text{keys.}$

(Changes are reflected to the MV as it is changed.)

See "7-8 Manual Output" (page 15) for more about changing to manual mode.

6. Parameter List

- The following explains each channel parameter.
 The list also shows the operational range of set values for parameters that are limited.
 When the PV input lower limit (Pvb), PV input upper limit (PvF), or decimal place position (Pvd) is changed, reconfigure all the initial parameter setting values.
 When the parameter that has [RESET] on its Remarks column is changed, turn off the power once, and then re-start the controller.

Ope							
		Parameter	Eurotion	Sotting range	Initial value	Bemarka	
Nº	Display	Name	Function	Setting range	Initial value	Remarks	
1	MRN	Switchover between auto and manual mode	Switchover between auto and manual modes	oFF (auto) / on(manual)	oFF	This parameter is not displayed in default setting. If you need to change this parameter, change the setting of "Ch11 dSP" so that it appears.	
2	5665	Switchover between RUN and standby	Switchover the operation mode between RUN and standby	oFF(RUN) / on(standby)	oFF		
3	REM	Local/remote switchover	Switches the operation between local/remote SV.	LoCL (local)/ REM (remote)	LoCL		
4	PRoC	Ramp soak control command	Changes ramp soak run states	oFF (stop)rUn (run)hLd (hold)	oFF	Displays End (when ending) or GS (during guaranty soak).	
5	RE	Auto-tuning run command	Runs auto-tuning.	oFF (stop/finish) on (normal type) L-oN (low PV type)	oFF		
6	LREH	Alarm output latch release command	Cancels the alarm output latch state	oFF / rST (latch resets)	oFF		
7	5¥N	SV selection	Chooses the SV No. used for control	LoCL Sv1 Sv2 Sv3 Sv4 Sv5 Sv6 Sv7 di (depending on DI)	LoCL	"When changing the SV with the front key, do not change the "Svn" parameter via communication. Otherwise, the changed SV may not be stored correctly."	
8	PL IM	PID selection	Chooses the PID No. used for control	LoCL Pid 1 (PID group No. 1) Pid 2 (PID group No. 2) Pid 3 (PID group No. 3) Pid 4 (PID group No. 4) Pid 5 (PID group No. 6) Pid 7 (PID group No. 6) Pid 7 (PID group No. 7) @id (depending on DI)	LoCL		
9	RI I		Sets the alarm value for ALM1.	Absolute value alarm: 0 to 100% FS	2.50%FS		
10	R I-L	ALM1 set value		Deviation alarm: -100 to 100% FS			
12	כוס		Sets the alarm value for ALM2	Absolute value alarm: 0 to 100% ES	2 50%ES		
13	92-1	AI M2 set value		Deviation alarm: -100 to 100% FS	2.007010		
14	82-H						
15	817	<u> </u>	Sets the alarm value for ALM3.	Absolute value alarm: 0 to 100% FS	2.50%FS		
16	83-1	ALM3 set value		Deviation alarm: -100 to 100% FS			
17	83-8						
18	RIY	ň	Sets the alarm value for ALM4.	Absolute value alarm: 0 to 100% FS	2.50%FS		
19	84-1	ALM4 set value		Deviation alarm: -100 to 100% FS			
20	R4-H						
21	RLS	Ĭ.	Sets the alarm value for ALM5.	Absolute value alarm: 0 to 100% FS	2.50%FS		
22	85-1	ALM5 set value		Deviation alarm: -100 to 100% FS			
23	R5-H						
27	WEMd	Electric power calculation command	Switches among on/off/hold of electric power calculation.	oFF (stop calculation) rUn (run calculation) hLd (suspend calculation)	oFF		
28	Lol	Key lock	Sets the key lock to prevent wrong operation	oFF (no lock) ALL (all lock) PArA (All but SV locked)	oFF		

Ch1 PID (control parameters)

	Parameter		Function	Sotting range	Initial value	Pomarke
N≌	Display	Name	Tunction	Setting range	initial value	ixemarks
50	P	Proportional band (%)	Sets the proportional band of the PID parameter.	0.1 to 999.9%	5.0%	
51	Ĺ	Integration time	"Sets the integration time of the PID parameter. Setting ""0"" will turn off integration."	0 to 3200 sec	240 sec	
52	d	Differential time	"Sets the differential band of the PID parameter. Setting ""0"" will turn off differentiation."	0.0 to 999.9 sec	60.0 sec	
53	HYS	ON/OFF control hysteresis	Sets the hysteresis width for the ON/OFF control.	0 to 50%FS	0.25%FS	
54	Cool	Cooling proportional band coefficient	"Sets the proportional band coefficient for cooling. Setting ""0.0"" will turn the cooling into an ON/OFF control."	0.0 to 100.0	1.0	
55	db	Dead band (%)	Shifts the cooling proportional band from the set value	-50.0 to 50.0%	0.0%	
56	ЬЯL	Output convergence value (%)	Offset value which is added to the MV output value	-100.0 to 100.0%	0/50 (single/dual)	
57	<i>RR</i>	Anti-reset windup	Sets the range of integration control	0 to 100%FS	100%FS	
58	REV	Normal/reverse operations	"Selects single control or dual control. Sets the control action (normal or reverse)."	rv- (heat (reverse)/cool (none)) no- (heat (normal)/cool (none)) rvno (heat (reverse)/cool (normal)) norv (heat (normal)/cool (reverse)) rvrv (heat (normal)/cool (reverse)) nono (heat (normal)/cool (normal))	rv/rvno (single/dual)	[RESET]
59	SI'L	SV limit (lower)	Sets the lower limit of SV	0 to 100%FS	0.00%FS	Note 1)
60	SI'H	SV limit (upper)	Sets the upper limit of SV	0 to 100%FS	100.00%FS	Note 1)
61	FEI	OUT1 proportion cycle	"Sets the proportion cycle of the control output (OUT1) (contacts, SSR drive)"	1 to 150 sec	30 (relay) 2 (SSR) 1 (current)	
62	£[2	OUT2 proportion cycle	"Sets the proportion cycle of the control output (OUT2) (contacts, SSR drive)"	1 to 150 sec	30 (relay) 2 (SSR) 1 (current)	
63	PLE I	OUT1 lower limit	Sets the lower limit of the control output(OUT1)	-5.0 to 105.0%	-5.0%	
64	PHE I	OUT1 upper limit	Sets the upper limit of the control output(OUT1)	-5.0 to 105.0%	105.0%	
65	PLE2	OUT2 lower limit	Sets the lower limit of the control output(OUT2)	-5.0 to 105.0%	-5.0%	
66	PHE2	OUT2 upper limit	Sets the upper limit of the control output(OUT2)	-5.0 to 105.0%	105.0%	
67	PEUE	Type of output limiter	Sets the type of output limiter	0 to 15	0	
73	RLPR	Alpha	Sets 2-degrees-of-freedom coefficient a	-199.9to 300.0%	40.0%	
74	ЬЕЕЯ	Beta	Sets 2-degrees-of-freedom coefficient β	0.0 to 999.9%	100.0%	

Note 1: "SvL" and "Svh" must be set so that SvL < Svh. When you change the values for "SvL" and "Svh", check SV 1 ("Sv1 Ch2") through SV 7 ("Sv7 Ch2").

Ch2 PLT (PID palette parameters)						
		Parameter				
N≌	Display	Name	Function	Setting range	Initial value	Remarks
100	51/1	SV1	Sets the SV (set value)	SV limit (lower)(SVL) to SV limit (upper)(SVH) %FS	0%FS	Note 1)
101	PI	Proportional band 1 (%)	Sets the proportional band.	0.1 to 999.9%	5.0%	
102	ET .	Integration time 1	Sets the integration time.	0 to 3200 sec	240 sec	
103	dl	Differential time 1	Sets the differential time.	0.0 to 999.9 sec	60.0 sec	
104	HYS I	ON/OFF control hysteresis 1	Sets the hysteresis when using the ON/OFF control.	0 to 50%FS	0.25%FS	
105	EoL I	Cooling proportional band 1 (%)	Sets the cooling proportional band.	0.0 to 100.0	1.0	
106	db l	Dead band 1 (%)	Sets the dead band	-50.0 to 50.0%	0.0%	
107	BAL I	Output convergence value 1 (%)	Offset value which is added to the control output	-100.0 to 100.0%	0/50 (single/dual)	
108	RR I	Anti-reset windup 1	Sets the anti-reset windup	0 to 100%FS	100%FS	
109	REV I	Normal/reverse 1	Selects single control or dual control. Sets the control action (normal or reverse).	rv- (heat (reverse)/cool (none)) no- (heat (normal)/cool (none)) rvno (heat (reverse)/cool (normal)) norv (heat (normal)/cool (reverse)) rvrv (heat (reverse)/cool (reverse)) nono (heat (normal)/cool (normal))	rv/rvno (single/dual)	Note 2) [RESET]
:	:	÷	:	•	•	•
160	51/7	SV 7	Sets the SV (set value)	SV limit (lower)(SVL) to SV limit (upper)(SVH) %FS	0%FS	Note 1)
161	PN	Proportional band 7 (%)	Sets the proportional band.	0.1 to 999.9%	5.0%	
162	17	Integration time 7	Sets the integration time.	0 to 3200 sec	240 sec	
163	d7	Differential time 7	Sets the differential time.	0.0 to 999.9 sec	60.0 sec	
164	8957	ON/OFF control hysteresis 7	Sets the hysteresis when using the ON/OFF control.	0 to 50%FS	0.25%FS	
165	Coll	Cooling proportional band 7 (%)	Sets the cooling proportional band.	0.0 to 100.0	1.0	
166	db7	Dead band 7 (%)	Sets the dead band	-50.0 to 50.0%	0.0%	
167	6RL7	Output convergence value 7 (%)	Offset value which is added to the control output	-100.0 to 100.0%	0/50 (single/dual)	
168	RR1	Anti-reset windup 7	Sets the anti-reset windup	0 to 100%FS	100%FS	
169	REI/7	Normal/reverse 7	Selects single control or dual control. Sets the control action (normal or reverse).	rv- (heat (reverse)/cool (none)) no- (heat (normal)/cool (none)) rvno (heat (reverse)/cool (normal)) norv (heat (normal)/cool (reverse)) rvv (heat (normal)/cool (reverse)) none (heat (normal)/cool (normal))	rv/rvno (single/dual)	Note 2) [RESET]
170	REF I	PID switching point 1	Sets the PID switching point for palette 1.	0 to 100%FS	0%FS	
:	:	:		•	•	•
176	REF7	PID switching point 7	Sets the PID switching point for palette 7.	0 to 100%FS	0%FS	
177	SV MX	Max SV selection number	Choosing SV with the user key sets it to the maximum possible number.	LoCL SV1 SV2 SV3 SV4 SV4 SV5 SV6 di (depending on DI)	Sv7	
178	PL IM	Max PID selection number	Choosing PID with the user key sets it to the maximum possible number.	LoCL Pid1 Pid2 Pid3 Pid4 Pid5 Pid5 Pid6 Pid7 di (depending on DI)	Pid7	

Note 1: "SvL" and "Svh" must be set so that SvL < Svh. When you change the values for "SvL" and "Svh", check SV 1 ("Sv1 Ch2") through SV 7 ("Sv7 Ch2"). Note 2: Set the same value as the one for the Normal/Reverse setting ("rEv Ch1").

Ch 3 PRG (ramp soak parameters)

		•••				
		Parameter	Function	Setting range	Initial value	Remarks
Nº	Display	Name				
200	PEN	Ramp soak operation pattern (Step No.)	Sets which steps to use in the ramp soak operation pattern	0 (uses steps 1 to 8) (1uses steps 9 to 16) 2(uses steps 25 to 32) 4(uses steps 25 to 32) 4(uses steps 25 to 32) 4(uses steps 41 to 48) 6(uses steps 41 to 48) 6(uses steps 41 to 56) (1uses steps 57 to 64) 8(uses steps 17 to 32) 10(uses steps 13 to 48) 11(uses steps 13 to 64) 12(uses steps 13 to 64) 14(uses steps 15 to 64) 14(use 15 to 64) 14(use 15 to 64) 14(use 15 to 64) 14(use 15 to	14	Note 1)
201	FIWN	Ramp soak time units	Sets the units of the ramp soak time	hh.MM (hour:min) MM.SS (min:sec)	hh.MM	
202	51/-1	Ramp soak 1 seg/SV 1	Sets the SV	0 to 100%FS	0%FS	
203	EM IR	Ramp soak 1 seg ramp time	Sets the ramp time.	00:00 to 99:59 (hour:min/min:sec)	00:00	
204	EM IS	Ramp soak 1 seg soak time	Sets the soak time.	00:00 to 99:59 (hour:min/min:sec)	00:00	
205	51/-2	Ramp soak 2 seg/SV 2	Sets the SV	0 to 100%FS	0%FS	
206	FWSb	Ramp soak 2 seg ramp time	Sets the ramp time.	00:00 to 99:59 (hour:min/min:sec)	00:00	
:	:	•	•	•	• •	•
389	£63R	Ramp soak 63 seg ramp time	Sets the ramp time.	00:00 to 99:59 (hour:min/min:sec)	00:00	
390	£635	Ramp soak 63 seg soak time	Sets the soak time.	00:00 to 99:59 (hour:min/min:sec)	00:00	
391	51/64	Ramp soak 64 seg/SV 64	Sets the SV	0 to 100%FS	0%FS	
392	£64R	Ramp soak 64 seg ramp time	Sets the ramp time.	00:00 to 99:59 (hour:min/min:sec)	00:00	
393	2645	Ramp soak 64 seg soak time	Sets the soak time.	00:00 to 99:59 (hour:min/min:sec)	00:00	
394	Mod	Ramp soak mode	Sets the program operation method	0 to 15	0	
395	65oK	Guaranty soak ON/OFF	Sets the guaranty soak ON or OFF	oFF (guaranty soak off) on (guaranty soak on)	oFF	
396	65-L	Guaranty soak band (Lower)	Sets the lower limit of guaranty soak	0 to 50%FS	1.25%FS	
397	65-H	Guaranty soak band (Upper)	Sets the upper limit of guaranty soak	0 to 50%FS	1.25%FS	
398	PV SE	PV start	Sets whether or not to start ramp soak with PV.	oFF (PV start off) on (PV start on)	oFF	
399	EoNE	Restore mode	Sets how to restart when the controller is restored after a power loss.	rES (Reset) Con (Continue) ini (Restart)	rES	
400	PENM	Max pattern selection	Sets the maximum pattern number selectable by using the user key.	0 to 14	14	
401	PMEN	Min pattern selection	Sets the minimum pattern number selectable by using the user key.	0 to 14	0	

Note 1: Do not change this parameter during the ramp soak operation. Be sure to set "PrG" = "oFF" before changing the parameter.

011 4							
		Parameter					
N≌	Display	Name	Function	Setting range	Initial value	Remarks	
420	SEAE	Ramp soak progress	Displays the progress of the ramp soak	oFF (ramp soak stopped) 1-rP (ramp in step 1) 1-Sk (soak in step 1)	_		
				64rP (ramp in step 64) 64Sk (soak in step 64) End (ramp soak finished)			
421	MV I	MV1(%)	Displays the output value of the control output (OUT1)	-5.0 to 105.0%	_		
422	MV2	MV2(%)	Displays the output value of the control output (OUT2)	-5.0 to 105.0%	-		
424	R51/	Remote SV	Shows a remote SV.	-5% to 105%FS	-		
425	[[]	Heater current (A)	Shows a heater current value. (A current value when OUT1 is ON.)	0 to 110.0 A	—		
427	LEI	SSR leak current (A)	Shows a leak current value. (A current value when OUT1 is OFF.)	0 to 110.0 A	—		
429	EMI	Remaining time on timer 1	Displays the remaining time on timer 1	0 to 9999 sec/ 0 to 9999 min	—		
430	FW5	Remaining time on timer 2	Displays the remaining time on timer 2	0 to 9999 sec/ 0 to 9999 min	-		
431	FW3	Remaining time on timer 3	Displays the remaining time on timer 3	0 to 9999 s/0 to 9999 min	—		
435	CoMM	Communication status	Displays the communication status.	0 to 9999 times (number of communication times)	—		
436	EURI	Current (A)	Shows a value measured by CT.	0 to 110.0 A	—		
438	PoW	Electric power	Shows a calculated value for electric power.	0.0 to 9999 KW	-		
439	KWH	Power	Displays the calculated amount of electric power.	0.0 to 999.9 Wh	—		
440	REN I	Number of opetating times (control relay 1)	Displayes the number of times that control relay 1 has operated.	0 to 9999k times	—		
441	RENZ	Number of opetating times (control relay 2)	Displayes the number of times that control relay 2 has operated.	0 to 9999k times	—		
442	RUNE	Operating days	Displays the number of days oparated, converted from total operating time.	0 to 5000 days	—		
443	FALE	Error source	Displays the source of an error	0 bit: PV input underflow (LULL) 1 bit: PV input overflow (UUUU) 2 bit: PV underrange 3 bit: PV overrange 4 bit: R-SV underrange 5 bit: R-SV overrange 6 bit: Rage setting error 8 bit: PV input circuit error 10 bit: CT input circuit error 10 bit: CT input circuit error	_		
444	dī	DI input state	Displays the state of DI.	0 bit Dl1 1 bit Dl2 2 bit Dl3	_		
445	ERSE	Communication error station number	Shows the station number under a cooperative communication error or a programless communication error.	1 to 31	_		
446	PLNo	Current palette No.	Displays the PID palette No. currently selected.	0-7	—		
447	PENo	Current pattern No.	Displays the pattern No. of the ramp soak currently selected.	0-15	_		

Ch 5	h 5 ALM (alarm parameters)						
Nº	Display	Parameter Name	Function	Setting range	Initial value	Remarks	
470	8 IF P	ALM1 alarm type	Set the alarm type for ALM1.	0 to 58	0	Refer to section 11 for the detail.	
471	RIHY	ALM1 hysteresis	Sets the hysteresis for alarm output 1 ON/OFF	0 to 50%FS	0.25%FS		
472	dIHI	ALM1 delay	Sets the delay before detecting alarm output 1	0 to 9999 [sec/min]	0		
473	dL IU	ALM1 delay time units	Sets the delay time units for alarm output 1	sec (second) Min (minute)	sec		
474	RoP I	ALM1 option	Assigns the optional functions to ALM1 Ones digit: alarm output latch Tens digit: error alarm Hundreds digit: hold reset Thousands digit: hold reset	0000 to 1111	0000		
:	:	•	•	•	•	•	
490	95LD	ALM5 hysteresis	Sets the hysteresis for alarm output 5 ON/OEF	0 to 50%ES	0.25%ES	Refer to Section 11 for the detail	
491	8589	ALM5 delay	Sets the delay before detecting alarm output 5.	0 to 9999 [sec/min]	0		
492	dL 95	ALM5 delay time unit	Sets the delay time unit for alarm output 5.	sec (second) Min (minute)	sec		
493	dL SU	ALM5 option	Assigns the optional functions to ALM5. Ones digit: alarm output latch Tens digit: error alarm Hundreds digit: inverted output Thousands digit: hold reset	0000 to 1111	0000		
494	RoP5	ALM5 option	Assigns the optional functions to ALM5 Ones digit: alarm output latch Tens digit: error alarm Hundreds digit: inverted output Thousands digit: hold reset	0000 to 1111	0000		
500	Hb I	HB alarm set value	Sets the value to activate the heater burnout alarm.	0.0 to 100.0 (A)	0.0A		
501	Hb IH	HB alarm hysteresis	Sets an ON/OFF hysteresis for the heater burnout alarm.	0.0 to 100.0 (A)	0.5A		
502	HS I	Shorted-load alarm set value	Sets the alarm value for heater shorted load.	0.0 to 100.0 (A)	0.0A		
503	HS IH	Shorted-load alarm hysteresis	Sets an ON/OFF hysteresis for the heater shorted-load alarm.	0.0 to 100.0 (A)	0.5A		
508	<i>LЪЕМ</i>	Loop break detection time	Sets the time before detecting a broken loop	0 to 9999 sec	0 (Off)		
509	LBAB	Loop break detection range (°C)	Sets the temperature range before detecting a broken loop	0.0 to 100.0%FS	2.50%FS		
511	WHAL	Electricity alarm	Sets the value for electricity alarm.	0-9999KWh	0		

	- (,	1			
No	Diamlau	Parameter	Function	Setting range	Initial value	Remarks
<u>№</u> 530	Display PVE	Name PV input type	Sets the type of input sensor	Setting range JPT1: 0.0 to 150.0°C JPT2: 0.0 to 300.0°C JPT3: 0.0 to 600.0°C JPT3: 0.0 to 600.0°C JPT6: -0.00 to 100.0°C JPT6: -100.0 to 200.0°C JPT6: -0.00 to 100.0°C JPT7: 0.0 to 500.0°C PT1: 0.0 to 500.0°C PT1: 0.0 to 500.0°C PT3: 0.0 to 500.0°C PT3: 0.0 to 500.0°C PT3: 0.0 to 100.0°C PT3: 0.0 to 100.0°C PT4: 0.0 to 600.0°C PT4: 0.0 to 100.0°C PT5: -50.0 to 100.0°C PT6: -50.0 to 100.0°C PT6: -50.0 to 100.0°C PT6: -50.0 to 100.0°C PT7: -199.9 to 600.0°C J3: 0.0 to 800.0°C PT7: -199.9 to 600.0°C K3: 0.0 to 800.0°C K4: 200 to 1300°C K3: 0.0 to 800.0°C E1: 0.0 to 740.0°C E3: -50.0 to 740.0°C	K1	Remarks [RESET] Refer to section 10 for the detail.
531	01/L	PV input lower limit	Sets the lower limit of PV input	-1999 to 9999	0	(RESET)
532	r*0 0/C		Sets the upper limit of PV input	1000 to 0000	400	
532	PV PVd	Decimal point position	Sets the decimal point position for the PV/SV	O: No digit after decimal point O: No digit after decimal point O: 10 digit after decimal point O: 2 digit after decimal point O: 3 digit after decimal point	0	[RESET]
535	ΓIIŀ	Square-root extractor cut point	Sets the cut point for square root calculation.	-0.1 to 105.0(%)	-0.1%	
536	PlinE	PV input shift	Sets the amount of shift for PV input	-10 to 10%FS	0.00%FS	
538	ŀF	PV input filter	Sets the time constant for the PV input filter	0.0 to 120.0 sec	5.0 sec	
543	REMo	Remote SV zero adjustment	Adjusts the zero side of remote SV.	-50 to 50%FS	0.00%FS	
544	REMS	Remote SV span adjustment	Adjusts the span side of remote SV.	-50 to 50%FS	0.00%FS	
545	REMR	Remote SV input range	Sets the range for remote SV input.	0-5v: 0 to 5 V 1-5v: 1 to 5 V 0-10: 0 to 10 V 2-10: 2 to 10 V	1-5V	
546	REF	Remote SV input filter	Sets the time constant for the RSV input filter	0.0 to 120.0 s	0.0 s	
547	E IR	OUT1 range	Sets the range of the control output 1(OUT1)	0-5v: 0 to 5 V 1-5v: 1 to 5 V 0-10: 0 to 10 V 2-10: 2 to 10 V 0-20: 0 to 20 mA 4-20: 4 to 20 mA	0-10 (voltage) 4-20 (current)	Displayed when OUT1 is current or voltage output.
548	E2R	OUT2 range	Sets the range of the control output 2(OUT2)	0-5v: 0 to 5 V 1-5v: 1 to 5 V 0-10: 0 to 10 V 2-10: 2 to 10 V 0-20: 0 to 20 mA 4-20: 4 to 20 mA	0-10 (voltage) 4-20 (current)	Displayed when OUT2 is current or voltage output.
549	FLo I	MV1 during FALT	Sets the output value for the control output (MV1) during	-5.0 to 105.0%	-5.0%	
550	FLoZ	MV2 during FALT	Sets the output value for the control output (MV2) during FALT	-5.0 to 105.0%	-5.0%	
551	SFo I	MV1 during Soft Start	Sets the value for the control output (MV1) during soft start	-5.0 to 105.0%	105.0%	
553	SFEM	Soft Start set time	Sets the time from startup to the finish of soft start	00:00 to 99:59 (hour:min)	00:00	Be sure to set 0.00 during dual control.
554	560 l	MV1 during standby	Sets the value for the control output (MV1) during standby	-5.0 to 105.0%	-5.0%	
555	5602	MV2 during standby	Sets the value for the control output (MV2) during standby	-5.0 to 105.0%	-5.0%	
556	56Md	Standby mode	Sets on/off of the alarm output during standby	0: ALM=OFF, AO=ON 1: ALM=ON, AO=ON 2: ALM=OFF, AO=OFF 3: ALM=ON, AO=OFF	0	[RESET]
557	Rot	AO	Selects what to transfer to the analog output.	PV SV MV DV PFb	PV	
558	HoL	AO lower scaling	Sets the AO lower scaling	-100.0 to 100.0%	0.0%	
559	НоН	AO upper scaling	Sets the AO upper scaling	-100.0 to 100.0%	100.0%	
561 562	VoLE CUR	Fixed voltage value Current value for simple power calculation	Sets the voltage for calculating electric power Sets the current value for simple power calculation	1 to 500V 0.0 to 100.0A	100 (100 V) 0 (0.0A)	
564	WdP	Decial point position for electric power	Sets the position of decimal point for calculationed power consumption.	0:0 1:0.1 2:0.01 3:0.001	1:0.1	Do not change it during calculation.
565	РНУ	Power factor for simple calculation	Sets the power factor for simple calculation	0.00 to 1.00	1.00	
566	RYEN	Upper limit of relay contact operation	Sets the upper limit on the number of times a relay contact can operate. If you set it to 0, no alarm will be generated.	0 to 9999	10 (10K times)	
567	oPtM	Upper limit of operating days	Sets the upper limit on the number of days the device	0 to 5000	3650 (3650 days)	

Cn /	515 (sy	stem parameters)				
		Parameter				
Nº	Display	Name	Function	Setting range	Initial value	Remarks
590	UKY 1	USER key	Assigns the function to the [USER] key	0 to 29	0	Refer to section 12 for the detail.
591	U#92	USER + UP key	Assigns the function to the [USER]+ Λ key	0 to 29	1	
592	UKY3	USER + DOWN key	Assigns the function to the [USER]+ V key	0 to 29	5	
593	dīl	DI-1 function select	Allocates a function to DI-1.	0-48	0	Refer to Section 14 for the detail.
594	dī2	DI-2 function select	Allocates a function to DI-2.	0-48	0	
595	dī 3	DI-3 function select	Allocates a function to DI-3.	0-48	0	
599	oll It	OUT1 output type	Selects the content to be output from OUT1	0 to 427	1	Refer to section 13 for the detail.
600	oUZŁ	OUT2 output type	Selects the content to be output from OUT2	0 to 427	2	
601	do It	DO1 output type	Selects the content to be output from DO1.	0 to 427	3	
602	doZt	DO2 output type	Selects the content to be output from DO2.	0 to 427	4	
603	do3t	DO3 output type	Selects the content to be output from DO3.	0 to 427	5	
604	do4t	DO4 output type	Selects the content to be output from DO4.	0 to 427	6	
605	doSt	DO5 output type	Selects the content to be output from DO5.	0 to 427	7	
607	LoUT	LED indicator assignment (OUT1)	Selects the content for OUT1 to indicate.	0 to 427	1	
608	LoU2	LED indicator assignment (OUT2)	Selects the content for OUT2 to indicate.	0 to 427	2	
609	LEVI	LED indicator assignment (Ev1)	Selects the content for EV1 lamp to indicate.	0 to 427	3	
610	LEV2	LED indicator assignment (Ev2)	Selects the content for EV2 lamp to indicate.	0 to 427	4	
611	LE#3	LED indicator assignment (Ev3)	Selects the content for EV3 lamp to indicate.	0 to 427	5	
612	LEV4	LED indicator assignment (Ev4)	Selects the content for EV4 lamp to indicate.	0 to 427	6	
613	LE#S	LED indicator assignment (Ev5)	Selects the content for EV5 lamp to indicate.	0 to 427	7	
614	LE¥6	LED indicator assignment (Ev6)	Selects the content for EV6 lamp to indicate.	0 to 427	0	
615	LSEb	LED indicator assignment (STBY)	Selects the content for STBY lamp to indicate.	0 to 427	12	
616	LMRN	LED indicator assignment (MANU)	Selects the content for MAN lamp to indicate.	0 to 427	13	
617	RMP	Ramp SV ON/OFF	Sets the ramp SV ON/OFF	oFF oN	ON	
618	RMPL	Ramp SV-Decline	Sets the slope for a falling SV during ramp SV operations	0 to 100%FS	0.00%FS	
619	RMPH	Ramp SV-Incline	Sets the slope for a rising SV during ramp SV operations	0 to 100%FS	0.00%FS	
620	RMPU	Ramp SV-slope time unit	Sets the unit of time for the slope during ramp SV operations	hoUr: slope temperature/hour Min: slope temperature/min	hoUr	
621	5178	Ramp SV - display mode	Displays the SV during ramp operations or the SV goal value on the SV display	rMP: ramping SV TrG: target SV	rMP	
622	EERL	Control method	Selects the control method.	oNoF: ON/OFF control Pid: PID control FUZy: Fuzy control SELF: Self-tuning control Pid2: PID2 control PId2: PID2 control 2FRE: 2-degrees-of-freedom PID	Pid	
623	PRES	Valve control mechanism	Selects a valve control mechanism.	SRV1: Servo control 1 SRV2: Servo control 2 PFb: Position feedback control	SRV1 (SrV1: without PFB) PFB (PFb: with PFB)	
626	SEMd	Start mode	Sets the operation mode during startup	AUTo: starts in AUTO mode MAn: starts in manual mode REM: starts in remote mode STbY: starts in standby mode	AUTO	
627	dt	Control operation cycle	Sets the control operation cycle.	0.1 to 0.9S, 1 to 99S	0.1S	
628	PLES	PID pallette switching method	Sets the method for switching among PID pallette.	0: selected PID № 1: selected SV № 2: PV	0	

Ch 8 MATH (calculation parameters)

Parameter		Parameter	Eurotien	Cotting range	Initial value	Demodra	
N≌	Display	Name	Function	Setting range	initial value	Reliaiks	
650	MREH	Simple calculation ON/OFF	Sets ON/OFF of simple calculation	OFF ON	OFF	Note 1)	

Note 1: Refer to the operation manual for the detail of calculation functions.

Ch 9	h 9 COM (communication parameters)							
		Parameter	Eurotion	0.111	Initial value	Duranta		
Nº	Display	Name	Function	Setting range	iiiiidi value	Reillaiks		
760	СЕУР	Communication type	Selects a type of communication.	0: MODBUS RTU 1: Cooperative operation 2: Programless communication	0	[RESET] Note 1)		
761	SENo	Station No.	Sets the station number.	0 to 255 (0: unresponsive communication)	1	[RESET]		
762	SPEd	RS-485 baud rate	Sets the baud rate	96: 9600 bps 192: 19200 bps 384: 38400 bps 115K: 115 Kbps	96	[RESET]		
763	PREY	RS-485 parity	Sets the parity check	none odd even	odd	[RESET]		
764	ΞΝΕV	RS-485 response interval	Widen the time interval of receiving response. (Set value × 20 ms)	0 to 100	1 (20 ms)	[RESET]		
767	500	Communication permissions	Sets whether or not overwriting is possible from the master side (PC, etc.)	r: Read only rW: Read/overwrite permitted	rW	[RESET]		
769	URD I	MODBUS user address setting 1	Sets the MODBUS user address		30001	[RESET]		
•	•	•	•	•	•	•		
		•	•	•	•			
800	UR32	MODBUS user address setting 32			30001	[RESET]		

Note 1: Refer to the communication instruction manual (MODBUS) for the detail of communication functions.

Ch 10 PFB (PFB parameters)

		• •				
Parameter			Function	Softing rongo	Initial value	Pomorko
N≌	Display	Name	Function	Setting range	iiiiidi value	Rellars
870	PGRP	PFB dead band	Sets the dead band for PFB.	0.0% to 100.0%	5.0%	
871	ERVL	Valve stroke time	Sets the full-stroke time for the motorized valve.	5 s to 180 s	30 s	
873	ERL	PFB input adjustment command	Adjusts the zero/span for PFB input.	0 (none/forcibly terminate) 1 (zero adjustment) 2 (span adjustment) 3 (automatic adjustment)	_	

Ch 1	h 11 DSP (parameter mask)					
Nº	Display	Parameter Name	Function	Setting range	Initial value	Remarks
-	_	Parameter mask	Sets the parameters to be displayed/not displayed.	OFF/diSP	Values differ depending on the model.	

Ch 1	2 CFG (0	configuration parameters)				
		Parameter				
Nº	Display	Name	Function	Setting range	Initial value	Remarks
940	ŁoUŁ	Operation timeout (return to PV/SV display)	Sets the time until the display returns to PV/SV screen from setting screen.	15S: 15 sec 30S: 30 sec 60S: 60 sec 5M: 5 min 10M: 10 min non	60S	
942	SoFK	Blinking SV during Soft Start	Sets whether or not to blink SV during Soft Start.	oFF: OFF oN: ON	ON	
943	RLMF	Blinking PV/SV at ALM	Sets whether or not to blink PV/SV when alarm becomes ON.	0: PV display (no change) 1: PV and alarm status, alternately 2: blinking PV 3: alarm status	0	
944	LoFF	Display timeout	Sets the time until the display automatically turns off.	oFF: Not use 15s: Auto-off after 15 sec. 30s: Auto-off after 30 sec. 1M: Auto-off after 1 min, 5M: Auto off after 5 min.	oFF	
945	dSPE	PV/SV Display off	Sets ON/OFF of PV and SV display	0: PV and SV ON 1: SV OFF 2: PV OFF 3: PV and SV OFF 4: PV, SV, and indicators OFF (all OFF) 4: PV, SV, and indicators OFF (all OFF) 6: PV OFF (relights for 5 sec. by pressing any key) 7: PV and SV OFF (relights for 5 sec. by pressing any key) 8: PV, SV, and indicators OFF(relights for 5 sec. by pressing any key)	0	
946	FALE	Blinking PV at input error	Sets whether or not to blink PV at an input error	0: PV blinks at an input error 1: No blink	0	
947	blīt	Brightness	Sets the brightness of LED backlight	0 to 3	3	(3 is the brightest)
948	bΣoN	Control at burnout	Sets whether to continue or to stop control when the device detects a burnout of PV input	oFF: stops control oN: continues control	oFF	
949	dMod	Display mode switchover	Switches between the two display modes.	dMd1: mode 1 (PXR mode) dMd2: mode 2 (PXF mode)	dMd2	[RESET]
950	PLO I	Model code	Shows model code	-	Р	
951	PLO2				Х	
952	PLO3				F	
:	:	•		•		•
962	PL 13				*	
963	RSE	Reset	Resets the controller	oFF: No reset rST: Performs reset	oFF	
965	VER I	Software version	Shows the software version	-	-	
966	VER2					
967	¥ER3					
968	IVER4					

Ch 13 PASS (password parameters)

Parameter			Function	0.00	Initial walve	Demortes
Nº	Display	Name	Function	Setting range	initial value	Remarks
990	PRS I	Password1 setup	Sets password 1.	0000 to FFFF	0000	
991	PR52	Password2 setup	Sets password 2.	0000 to FFFF	0000	
992	PR53	Password3 setup	Sets password 3.	0000 to FFFF	0000	

This controller has six types of temperature control function. Select according to type and use.

Caution The be	e ramp soak function (\prod page 15), and SV selection function (\prod combined.	page 17) cannot
Temperature Contr	rol Functions	
ON/OFF (2-position) control	Turns the control output ON/OFF according to the size relationship of PV and SV Can build a control system out of simple elements such as SSR. Suitable when accuracy is not requested.	7-1 (page 14)
PID Controls	PID calculation and controls proceed according to the previously set PID parameters. PID parameters can be set manually or through auto- tuning (AT). It is the most basic control in this equipment.	7-2 (page 14)
Fuzzy PID Control	PID control with function that reduces the amount of overshoot during control. It is effective when you want to suppress overshoot when SV is changed, even if you may take a long time to reach the target value.	7-3 (page 14)
Self-tuning Control	Automatically calculating PID control according to the control target or SV change. It is effective when the control conditions change frequently.	7-4 (page 14)
PID2 Control	In case which the power supply of the control target goes ON \to OFF \to ON, this PID2 control can suppress the amount of overshoot during control target turns OFF \to ON.	7-5 (page 15)
2-degrees-of-freedom control	Suppresses the amount of overshoot during PID control. It uses SV filter which is effective in reducing overshoot after a SV change or at startup.	7-6 (page 15)

7-1. ON/OFF (2-position) Control

Acts as an ON/OFF control when "[LBL" = $_{0}H_{0}F$ ("545 [h "). ON/OFF control switches the control output to ON (100%) or OFF (0%) according to the size relationship of PV and SV.The output hysteresis can be set under the parameter "H45" (" $P_{L}J$ [h !").

Reverse Operation (heat control)

Method used to control the electrical heating furnace. Set the "hYS" to an appropriate value according to the control target.

Parameter	Set value	r r
"[<i>ERL</i> "	oNoF	
"REI/"	rv	-
"#95"	arbitrary (factory setting: 1 °C)	-



Normal Operation (cooling control)

Method used to	control the cooling machine	
Parameter	Set value	F
"[ERL"	oNoF	
"REV"	no	
-445-	arbitrary (factory setting: 1 °C)	



Point

Refer to

 During ON/OFF control, the P, I and D settings do not affect control.
 The manual operation during ON/OFF control will become MV=100% when the ⊗ key is pressed, and MV=0% when the ⊗ key is pressed.
 If the hysteresis with this narrow, and PV and SV are nearly equal, the output may frequently switch ON and OFF. Note that it may affect the operation life of the contact context. output.

7-2. PID Controls

PID controls run as long as the parameter is set to "[LR]" = P_Ld ("545 [h7"). The PID controls calculate PID based on the set values for parameters "P", "L", "d", and "RR", and output the calculated result (-5% to 105%). Each parameter can be set either by manually tuning the values or by running auto-tuning (AT) to

automatically set the values.

For more details on auto-tuning, see "7-7 Auto-tuning" (page 15)

Display the system menu ("555 [h]").

Display the control parameter ("[LRL") and choose PID controls (" P_Ld ").

Press the (SEL) key to set the value.

7-3. Fuzzy PID Control

Related to normal PID controls, fuzzy PID control acts with small overshoot. You will need to run auto-tuning to set the PID parameter when using fuzzy control.

Setting fuzzy PID control

1	Display the system menu ("לַלָּל [h איי).
2	Display the control parameter ("[<code>LRL</code> ") and choose fuzzy (" <code>FUJ2</code> ")
3	Press the (SEL) key to set the value.

Refer to	For more details on auto-tuning, see "7-7 Auto-tuning" (page 15)

7-4. Self-tuning Control

Self-tuning Control is a control which automatically calculates the value of PID, under the condition that the control target or set value (SV) changes. Self-tuning is especially effective for situations when a high level of control is not needed, but autotuning cannot be run due to frequent changes in the control target conditions.

When a high level of control is required, choose PID control, fuzzy PID control, or PID2 control. Point

Conditions where self-tuning can be used

Self-tuning is used in the following situations

- When temperature rises when the power is turned on
 When temperature rises when SV changes (or when the controller decides it is necessary) . When the controller decides it is necessary because the controls have become unstable
- Conditions where self-tuning cannot be used

Self-tuning cannot be used in the following situations

- During control standbyDuring auto-tuning
- During ramp soak progress
 When there is error input
- When set for dual output
 When any of the P, I, D, Ar parameters are set to manual
- · During manual mode During soft start progress

Conditions to halt self-tuning

Halt self-tuning in the following situations:

- When there is a change in SV (This includes the case where SV changes because of the ramp soak function, remote SV function, or ramp SV.)
- . When self-tuning has not finished after running for nine or more hours

Setting self-tuning

Turn on power of the controller and set the SV

Display the system menu ("545 [h]").

Display the controller parameter ("[LRL") and choose self-tuning ("SELF").

Press the (sel) key to set the value.

Turn off power of the controller



1

2

3

4

Turn on power of the control target equipment and the controller. Turn on power of the control equipment first. Self-tuning will begin.

t



 The equipment will not tune correctly if power of the controller is turned on first.
 To reset self-tuning, set the control method to PID ("P_Ld") once before changing back to Point self-tuning.

7-5. PID2 Control

In the case which the power supply of the control target goes $\text{ON} \rightarrow \text{OFF} \rightarrow \text{ON},$ this PID2 control can suppress the amount of overshoot.

This control introduces an algorithm to prevent the calculated PID result from becoming a miscalculation, even when the control loop is open.

You will need to run auto-tuning to set the PID parameter when using PID2 control.

Features of PID2 Control



Setting PID2 control

Display the system menu ("545 [h]")

Display the control parameter ("[LRL") and choose PID2 (" $P_L d_L^{2"}$).

Press the (SEL) key to set the value.

7-6. 2-Degrees-of-Freedom PID Control

Suppresses the amount of overshoot during PID control. It uses the SV filter which is effective in reducing overshoot after a SV change or at startup.

Controllability in 2-degrees-of-freedom PID control is different depending on the setting of the coefficient α and β.

When the coefficient α = 100.0% and coefficient β =0.0% , the system performs the normal PID control.

You can adjust the coefficient α and β as follows: 1)Set the coefficient α to 40.0% and β to 100.0%. (factory default setting)

2)Perform a control to check the response (small overshoot). If overshoot is not reduced by this measure, adjust the coefficient α and β in accordance with the following table

We recommend you to fix the coefficient α to 40.0% because it usually requires no adjustment

Control result	Coefficient B	coefficient a
Large overshoot	Raise coefficient ß by 20%	Lower coefficient a by10%
Small overshoot	Lower coefficient ß by 20%	Raise coefficient a by10%

Setting 2-degrees-of-freedom PID control

Display the system menu ("555 [h7").

Display the control parameter ("[LRL") and choose 2-degrees-of-freedom PID ("2FRE").

Press the (SEL) key to set the value.

7-7. Auto-tuning

Run auto-tuning to set the PID parameter automatically.

"#L" set value	Behavior	Function
"oFF "	Stop/Finish	Stops or finishes auto-tuning.
"oN"	Normal type	The standard auto-tuning for SV reference. Choose this auto-tuning in most situations.
"L - oN"	Low PV type	Auto-tuning for SV-10% reference. Choose this when you want to suppress the overshoot when tuning.

Low PV type

Normal type





Set the following parameters before running auto-tuning. • PV input type / PV input upper limit / PV input lower limit / Decimal position / PV input filter in the setup channel menu (" $5_{L}^{L} (f_{h}^{m})$ ") • OUT1 proportion cycle (OUT2 proportion cycle) in the PID channel menu (" $P_{L}^{-}d (f_{h})$ "). Point

Running auto-tuning



AT lamp point will blink at the bottom of the display during auto-tuning. When auto-tuning has successfully completed, blinking AT lamp will turn off and overwrites the PID.

- PID parameter which is set after auto tuning has finished normally will be maintained even when the power is turned off. However, the PID value will not be changed if the power is turned off during auto- tuning. In this case, rerun auto-tuning. The equipment will use ON/OFF (2 position) control during auto- tuning, so there may be a large change in PV according to the process. Do not use auto-tuning for processes that do not permit a large change in PV. Do not use auto-tuning for processes such as pressure control and flow control that have a fast response.
 Auto-tuning is not behaving normally if it has not finished after four or more hours have passed. In these cases, recheck parameters such as input/output wiring, control output behavior (normal/ reverse), and input sensor type.
 Rerun auto-tuning if there is a large change in SV, a change in the control arget conditions that reduces the effectiveness of the controls.
 You can run auto-tuning when the control type is set to "fuzzy" or "PID2".

- You cannot run auto-tuning in manual mode.
 When using the PID selection function, the auto-tuning result for the selected PID group is stored
- Auto tuning is forcibly terminated when SV changes because of the ramp soak function, remote SV function, or ramp SV.

7-8. Manual Output

Point

Allows the control output to be manually set at an arbitrary value.

 Manual Mode Display MV indiator lights during manual mode and during parameter setting.

- Switchover between Auto and Manual Modes can be changed by three methods: the front key (user key), communication function, or the parameter "MRN"
- MV output flow diagram (MV output priority processing)



 MV limit does not apply to the MV output during manual operation, FALT, or standby. (Take extra caution when MV performs flash protection during combustion control by using the overlimit function.) Caution

7-9. Ramp Soak Function

Automatically runs after setting the times for the SV changes.







Creating a ramp soak operation pattern

Set the following	g items to create a pattern.
Pattern	Sets which steps to use from the following 15 types. Steps 1 to 8 / Steps 9 to 16 / Steps 17 to 24 / Steps 25 to 32 / Steps 33 to 40 / Steps 41 to 48 / Step 49 to 56 / Steps 57 to 64 / Steps 1 to 16 / Steps 17 to 32 / Steps 33 to 48 / Steps 49 to 64 / Steps 1 to 32 / Steps 33 to 64/ Steps 1 to 64
Target SV	Sets the controlled temperature.
Ramp time	Sets the time to reach the target SV from the current SV.

The following steps will explain how to run the specified pattern 0 in SV-1 to SV-8.

Display the ramp soak menu ("PRL [h]").

Soak time

Display pattern parameter ("PEN") and choose pattern 0 ("D").

Sets the time to maintain the specified SV.

	Run SV-1 through SV-8.
3	Display the time parameter (" L_LMU ") and choose minute:second ("MM55"). Sets the units of time. Besides minute:second ("MM55"), you can also choose hour:minut ("HHMM")
4	Display the target value ("5" - h ") and set the target temperature.
5	Display the ramp time parameter ("L^{ \!\!\!/} / / \!\!\!/ / \!\!\!\!/ \!\!\!\!\!\!\!\!\!\!\!\!\!\!\!
6	Display the soak time parameter (" $L^{\prime\prime}_{L}/J^{\prime\prime}_{l}$) and set the soak time.
7	Repeat steps 4 through 7 and set the remaining parameters.

Running ramp soak

The following steps explain how to run ramp soak



2 Ramp soak starts running from the current PV.

Point

 To interrupt the ramp soak operation, choose HOLD ("HLd") in step 2. To cancel the interruption, choose RUN ("P[i]h") again.
 "End" will display when ramp soak has completed.

Guaranty soak

This function guarantees the soak time. Only soak time within the specified range of temperature for SV is counted towards soak time. As seen in the figure below, only the sum of the shaded areas is counted as soak time. The operation

As seen in the figure below, only the sum of the shaded areas is counted as soak time. The operatio moves onto the next step when the total soak time equals the specified soak time.



The following steps will explain how to set an example guaranty soak range with an upper limit of 5°C and a lower limit of 3°C.

1 Display the ramp soak menu ("PR[H]").

2 Display guaranty ON/OFF parameter (" $[J_0]$ ") and choose on (" $_0$]").

- 3 Display the guaranty soak lower limit parameter ("[5-L") and set the lower limit (in this example, set it to 3°C).
 - Display the guaranty soak upper limit parameter ("[5-H") and set the upper limit (in this example, set it to 5°C).
- 5 Press the (SEL) key to set the value.

Mode setting

Sets how you want to run ramp soak.

The	follow	/ina	items	can	he	set

Power On Start	Ramp Soak starts running from the current PV.	
Ending Output Shows the ending output after ramp soak has been completed.		
OFF Output	Shows the output during OFF after ramp soak has been completed.	
Repeat Behavior	After finishing the last step in ramp soak, the process starts again from 1st step.	



You can choose from the following 16 types of modes according to the combination of run method options.

Setting	Power On Start	Ending Output	OFF Output	Repeat Behavior
"0"	Off	Continuous control	Continuous control	Off
"1"	Off	Continuous control	Continuous control	On
"2"	Off	Continuous control	Standby	Off
"3"	Off	Continuous control	Standby	On
"4"	Off	Standby	Continuous control	Off
"5"	Off	Standby	Continuous control	On
"6"	Off	Standby	Standby	Off
"7"	Off	Standby	Standby	On
"8"	On	Continuous control	Continuous control	Off
"9"	On	Continuous control	Continuous control	On
"10"	On	Continuous control	Standby	Off
"11"	On	Continuous control	Standby	On
"12"	On	Standby	Continuous control	Off
"13"	On	Standby	Continuous control	On
"14"	On	Standby	Standby	Off
"15"	On	Standby	Standby	On

PV start

When the ramp soak starts (RUN), this function searches the first point where the measurement value (PV) and the program pattern match, and starts operation at that point.



If the measurement value does not match the pattern as with PV = (3), the normal operation starts.

7-10. Other Functions

1. Soft start function

When turning on the equipment (including the temperature controller), the soft start function suppresses the MV to become maximum output. It places an upper limit on MV output for a specified amount of time after power is turned on.

This function is useful for effects such as suppressing the heater output during equipment startup, and makes load lightened.

After the specified time has passed after switching on the equipment (or if SFTM = 0), the soft start function ends and normal controls begin.

Display	Parameter	Function			
"5Fo /" (SFo1)	MV1 soft start output set value	Places a limit on MV1 output after power is turned on for a time period set in SFTM.			
"5F <i>LM</i> " (SFTM)	Soft start set time	Sets the time for soft start to function after turning power on. Setting "0" will turn off soft start.			



Caution

The soft start function cannot be used simultaneously with the dual control



2

During manual mode, the manual output value has priority, but soft start will continue to keep track of the set time period.

Use the following steps to set soft start output set value and set time.



Display the setup menu ("5Fa /").

Display soft start set time ("5FLM") and set the time.



5 Turn off the power once, and then re-start the controller to begin soft start. (When the soft start function is turned on, the lower display will alternate showing SoFT and SV.) Note: Do not use auto-tuning at the same time.

U





When the user key function code is 27 (SV No.+1, PID No.+1 (send)) and the initial PID No. and SV No. are different, the first time you press the user key, PID No. will become the No. and SV No. Also the SVMX parameter value becomes the maximum selectable number for PID No.

• Switch Using Parameter "Pl IM" via the Communication Channel In the communication, overwrite the set value to the selected SV number ("PL IM").

7. Startup mode function

The startup mode specification function sets the controller to start up in any of auto mode, manual mode, remote mode or standby mode. It is used when you want to start up in manual mode

Use the following steps to set this function



Display the system menu ("555 [h]")

Display the startup mode ("5LMd") and choose the operational mode. Choose from auto or manual.

Press the (SEL) key to set the value.

After changing the above setting, restarting the controller will start it in the selected mode.

Point When starting up in manual, the MV becomes 0%.

8. User function key

Pressing the O key in the parameter screen will immediately return you to the PV/SV display, regardless of assigned function. Holding the O key, O key + \bigotimes key, or O key + \bigotimes key down for about a second in PV/SV display or PV/MV display will run the assigned function.



For functions that can be assigned, see "12 USER key assignment" (page 21).

Use the following steps to set this function.



Display the assign user key specification (" $\ensuremath{\textit{U}}\xspace{\ensuremath{\textit{H}}\xspace{\ensuremath{\textit{U}}\xspace{\ensuremath{\textit{N}}\xspace{\ensuremath{N}\xspace}\ensuremath{N}\xspace{\ensuremath{N}\xspace{\ensuremath$

Press the (SEL) key to set the value.

9. bAL and Ar functions

• The anti-reset windup function ("RR") cuts integration that falls outside of the Ar set range that is centered around SV. Running auto-tuning will set the optimum values for P, i, and d parameters, as well as Ar.



• The output convergence value function ("bAL") outputs to PV and SV a calculated result of the PID computed MV plus the bAL offset. (The factory setting of bAL is 0% for single output, 50% for dual output.)



Point Ar1 to Ar7 and bAL1 to bAL7 have the same function as in each PID group

10. MV limit functions

The MV limit function allows you to choose whether to limit the MV or let it pass through maxi- mum and minimum MV.

	DOUT	MV1		MV2	
output value	FCUI	PHC1	PLC1	PHC2	PLC2
PHC	"0"	103%	-3%	103%	-3%
	"1"	103%	limit	103%	-3%
	"2"	limit	-3%	103%	-3%
	"3"	limit	limit	103%	-3%
limit	"4"	103%	-3%	103%	limit
	"5"	103%	limit	103%	limit
	"6"	limit	-3%	103%	limit
	"7"	limit	limit	103%	limit
PLC	"8"	103%	-3%	limit	-3%
	"9"	103%	limit	limit	-3%
	"10"	limit	-3%	limit	-3%
	"11"	limit	limit	limit	-3%
PLC PHC output value PLC (before limit)	"12" "13" "14" "15"	103% 103% limit limit	-3% limit -3% limit	limit limit limit limit	limit limit limit limit

8. Setting the Temperature Controller

8-1. Input Setting

Set the type and the range for input sensor. Input can be set in the setup menu ("5EL [h_{b} "]. For more on input types, input scaling, decimal point location, and input codes, see "10 Input Range For more on input types, input scaling, decimal point location, and input codes, see and Codes (standard range)". (page 19)



8-2. Output Setting

Sets the control output. (Only when the output is current or voltage.)

Sets the range of the control output (OUT1, OUT2) ("[IR " " [2R Choose any of 0 to 5V, 1 to 5V, 0 to 10V, 2 to 10V, 0 to 20mA or 4 to 20mA DC.

8-3. Control Setting

- Sets controls to normal operation or reverse operation.
- Reverse operation: As the process value (PV) rises, the control output (MV) becomes smaller. Used to heat the control object.
- . Normal operation: As the process value (PV) rises, the control output (MV) becomes larger. Used to cool the control object.

1. Se Choose	t the normal any of the fo	or reverse operat	את ("אָבָּוֶ") ons of heat and cool to suit your system.
rEv	Control	Control	
	output 1	output 2	
rv	Reverse	-	
no	Normal	-	
rvno	Reverse	Normal	
norv	Normal	Reverse	
rvrv	Reverse	Reverse	
nono	Normal	Normal	

Error Indications 9.

9-1. Display During Equipment Error

This controller has a display function to indicate several types of error code shown below. If any of the error code is displayed, please eliminate the cause of error immediately. After the cause is eliminated, turn off the power once, and then re-start the controller.

Display	Possible cause	Control output				
"UUUU"	 Thermocouple burnout. Resistance bulb sensor (A) burnout. PV exceeds upper limit of the range by 5%FS. 					
·!!!!	 Resistance bulb sensor B or C wire burnout. Resistance bulb sensor (between A & B or A & C) short. PV is belC) short. PV is belC) wore limit of the range by 5% FS. Burnout or short in the voltage input. 	Output as setting value when an error occurs (set in parameter Flo1 or Flo2)				
-1111-	(1) PV < -199.9	Control operation is continued Note) Control operation is continued as long as the accuracy is above -5%FS. When the accuracy declines to be lower than -5%FS, the controller outputs the specified value for an error.				
"ERR" (SV flickers)	Incorrect setting (Pvb/PvF)	The controller outputs the specified value for an error. (The value can be set in parameter Flo1 or Flo2)				
PV is not displayed	Check the set value of DSPT.	Normal control * The controller does not have to be restarted				
SV is not displayed	Check the set value of DSPT.	Normal control * The controller does not have to be restarted				
Parameters may not be displayed	Check the settings of Ch11 DSP	Normal control * The controller does not have to be restarted				

10. Input Range and Codes (standard range)

Inpu	it type	Input code (PVT)	Measurement range (°C) (PVb, PVF)	Minimum input increment (°C)	Measurement range (°F) (PVb, PVF)	Minimum input increment (°F)
RTD JPt 100		JPT1	0.0 to 150.0	0.1	32.0 to 302.0	0.1
JIS (IEC)		JPT2	0.0 to 300.0	0.1	32.0 to 572.0	0.1
		JPT3	0.0 to 500.0	0.1	32.0 to 932.0	0.1
		JPT4	0.0 to 600.0	0.1	32 to 1112	1
		JPT5	-50.0 to 100.0	0.1	-58.0 to 212.0	0.1
		JPT6	-100.0 to 200.0	0.1	-148.0 to 392.0	0.1
		JPT7	-199.9 to 600.0	0.1	-328 to 1112	1
	Pt 100	PT1	0.0 to 150.0	0.1	32.0 to 302.0	0.1
		PT2	0.0 to 300.0	0.1	32.0 to 572.0	0.1
		PT3	0.0 to 500.0	0.1	32.0 to 932.0	0.1
		PT4	0.0 to 600.0	0.1	32 to 1112	1
		PT5	-50.0 to 100.0	0.1	-58.0 to 212.0	0.1
		PT6	-100.0 to 200.0	0.1	-148.0 to 392.0	0.1
		PT7	-199.9 to 600.0	0.1	-328 to 1112	1
		PT8	-200 to 850	1	-328 to 1562	1
Thermocouple	J	J1	0.0 to 400.0	0.1	32.0 to 752.0	0.1
		J2	-20.0 to 400.0	0.1	-4.0 to 752.0	0.1
		J3	0.0 to 800.0	0.1	32 to 1472	1
		J4	-100 to 1000	1	-148 to 1832	1
	К	K1	0 to 400	0.1	32 to 752	0.1
		K2	-20.0 to 500.0	0.1	-4.0 to 932.0	0.1
		K3	0.0 to 800.0	0.1	32 to 1472	1
		K4	-200 to 1300	1	-328 to 2372	1
	R	R	0 to 1700	1	32 to 3092	1
	В	В	0 to 1800	1	32 to 3272	1
	S	S	0 to 1700	1	32 to 3092	1
	Т	T1	-199.9 to 200.0	0.1	-199.9 to 392.0	0.1
		T2	-199.9 to 400.0	0.1	-199.9 to 752.0	0.1
	E	E1	0.0 to 800.0	0.1	32 to 1472	1
		E2	-150.0 to 800.0	0.1	-238 to 1472	1
		E3	-200 to 800	1	-328 to 1472	1
	L	L	-100 to 850	1	-148 to 1562	1
	U	U1	-199.9 to 400.0	0.1	-199.9 to 752.0	0.1
		U2	-200 to 400	1	-328 to 752	1
	N	N	-200 to 1300	1	-328 to 2372	1
	W	W	0 to 2300	1	32 to 4172	1
	PL-II	PL-2	0 to 1300	1	32 to 2372	1
DC voltage	0 to 5 V DC	0-5V				
	1 to 5 V DC	1-5V				
	0 to 10V DC	0-10	-1999 to 9999		-1999 to 9999	
	2 to 10V DC	2-10	(Range where	-	(Range where	-
	0 to 100mV DC	MV	scalling is allowed)		scalling is allowed)	
DC current	0 to 20 mA DC	0-20				
1	4 to 20 mA DC	4-20	1	1	1	1

11. Alarm Action Type Codes

Туре	A1Tp to A5Tp	Alarm Type	Action diagram
	0	No alarm	_
Absolute value alarm	1	High alarm	PV ALn
	2	Low alarm	ALn t
	3	High alarm (with hold)	PV ALn
	4	Low alarm (with hold)	ALn t
Deviation alarm	5	High alarm	SVALn
	6	Low alarm	SV
	7	High/Low alarm	SVALn
	8	High alarm (with hold)	PV▲ SVALn t
	9	Low alarm (with hold)	SVAL'n
	10	High/Low alarm (with hold)	SV ALn
Zone alarm	11	High/Low deviation alarm	SV ALnL

Type	ATTPIOASTP	Alami Type	Action diagram
High/Low limit alarm	16	High/Low absolute alarm	PV AALnh ALnh ALnL
	17	High/Low deviation alarm	SV ALnh
	18	High absolute/Low deviation alarm	PV ALnh SV ALnL ► t
	19	High deviation/Low absolute alarm	SV ALnh ALnh
	20	High/Low absolute alarm (with hold)	PV AALnL ALnL ALnL
	21	High/Low deviation alarm (with hold)	PV ALnh SV ALnh t
	22	High absolute/Low deviation alarm (with hold)	PV ▲ ALnh SV → ALnL → t
	23	High deviation/Low absolute alarm (with hold)	PV A SV ALnh ALnh ► t
Zone alarm	24	High/Low absolute alarm	PV AALnh ALnh F t
	25	High/Low deviation alarm	PV ▲ SV → ALnh sv → t
	26 High absolute/L alarm	High absolute/Low deviation alarm	PV SVALnh ALnL ► t
	27	High deviation/Low absolute alarm	SV ALnh ALnh
	28 High/Low absolute ala (with hold)	High/Low absolute alarm (with hold)	PV AALnh ALnh P t
	29	High/Low deviation alarm (with hold)	PV ALnh SV ALnh t
	30	High absolute/Low deviation alarm (with hold)	PV ▲ SV → ALnh ALnh ↓ t
	31	High deviation/Low absolute alarm (with hold)	SV ALNH

Timer Code, other

Dual Set Value Alarm Codes

Туре	A1Tp to A5Tp	Alarm Type	Action diagram
Timer	32	ON delay timer	DI
	33	OFF delay timer	
	34	ON/OFF delay timer	DIALM
Ramp soak delay start	35	Delay start ON	
Open circuit and short circuit	37	Open loop alarm	
	38	Heater burnout alarm (Optional CT is required)	
	41	Shorted load alarm (Optional CT is required)	
Power	45	Amount of electric energy	
Maintenance	46	Preventive maintenance. The number of times that the relay has operated (MV1, MV2)	
	47	Preventive maintenance. Operated hours	



- When alarm action code is changed, alarm set value may also become different from previous settings.
 When alarm action type code is changed, turn off the power once, and then re-start the controller, before starting control.
 Aln: AL.1 to AL5 show the alarm set values
 ALnh: AL1h to AL5h show the alarm set values
 ALnh: AL1 to AL5 show the alarm set values
 ALnh: AL1 to AL5 show the alarm set values
 ALnh: AL1 to AL5 show the alarm set values
 ALnh: AL1 to AL5 show the alarm set values

* Other than the alarm setting, each of the event output functions can be assigned to DO1 to 5. For more details on each of the event output functions, refer to "13. OUT, DO, indicators assignment" (page 21).

12. USER key assignment

Caution

UkY 1 to 3 set value	Key function
0	No function
1	Switchover between STBY ON/OFF
2	Switchover between Auto/Manual
3	Switchover between Locul/Remote
4	Setting unavailable
5	Starts AT (standard)
6	Starts AT (low PV)
7	Setting unavailable
8	Ramp SV HOLD
9	Ramp soak RUN/OFF
10	Ramp soak RUN/HOLD
11	Setting unavailable
12	Latch release (all)
13	Latch release (ALM1)
14	Latch release (ALM2)
15	Latch release (ALM3)
16	Latch release (ALM4)
17	Latch release (ALM5)
19	Start timer (ALM1)
20	Start timer (ALM2)
21	Start timer (ALM3)
22	Start timer (ALM4)
23	Start timer (ALM5)
25	SVNo. + 1 (send)
26	PID No. + 1 (send)
	Setting upavailable
27	
27 28	Ramp soak pattern No. + 1 (send)

13. OUT, Alarm output, indicators assignment

OUT (Relay/SSR)	OUT (Current/ Voltage)	Alarm output	Indicator	Catagori	Function
oU1T, oU2T	oU1T oU2T	do1T, do2T, do3T, do4T, do5T	LoU1, LoU2, LEV 1 to 3, LSTb, LMAN	Category	Function
0	0	0	0		None
1	1	1	1	Control output	MV1 (heating)
2	2	2	2		MV2 (cooling)
3	_	3	3	Alarm output	Alarm 1
4	_	4	4		Alarm 2
5	_	5	5		Alarm 3
6	_	6	6		Alarm 4
7	_	7	7		Alarm 5
10	_	10	10	Status output	During auto-tuning startup
11	_	11	11		Normal
12	_	12	12		Standby
13	_	13	13		During manual mode
14	_	14	14]	During remote SV operation
15	_	15	15		During ramp SV
16	_	16	16	1	System error
20	_	20	20	Ramp soak	OFF
21	_	21	21	event output	RUN
22	_	22	22		HOLD
23	_	23	23		GS (Guaranty soak)
24	_	24	24		END
170	_	170	170	Ramp soak	Time signal (step 1 ramp)
171	_	171	171	Time signal	Time signal (step 1 soak)
172	_	172	172		Time signal (step 2 ramp)
173	_	173	173		Time signal (step 2 soak)
:	•	:	:		•
:		:	•		:
294	_	294	294]	Time signal (step 63 ramp)
295	_	295	295		Time signal (step 63 soak)
296	_	296	296]	Time signal (step 64 ramp)
297	—	297	297		Time signal (step 64 soak)
300	_	300	300	Ramp soak	Time signal (1st step ramp)
301	_	301	301	signal	Time signal (1st step soak)
302	_	302	302		Time signal (2nd step ramp)
303		303	303]	Time signal (2nd step soak)
•	•	:	•		•
	•]	•
424	_	424	424		Time signal (63rd step ramp)
425	_	425	425		Time signal (63rd step soak)
426		426	426]	Time signal (64th step ramp)
427	_	427	427		Time signal (64th step soak)

14. Model Specifications

You can allocate one of the following functions to each of DI1, DI2, and DI3. These functions are activated by external DI signals.

No	Function	Action	ON	OFF	Critorio
0	No function	No action	ON	011	Chiena
1	Standby ON/OFF awitchaver	Switches between Standby ON/OEE	Standby	Capacia Standby	Edgo
2		Switches the centrel output action between outp/manual	Manual	Auto	Edge
2		Switches the control output action between auto/manual.	Romoto	Auto	Edge
3	No function	Net for upo	Remote	LUCAI	Euge
4			Ctart		
5	Auto tuning (standard) start	Runs standard auto-tuning.	Start	Stop	Edge
6	Auto tuning (low-PV) start	Runs low-PV type auto-tuning.	Start	Stop	Edge
7	Ramp SV ON/OFF	Enables or disables ramp SV.	Disable	Enable	Edge
8	Ramp SV hold	Switches between ramp SV hold and hold cancel.	Hold	Hold cancel	Edge
9	Ramp soak RUN/OFF	Switches between ramp soak RUN/OFF.	RUN	OFF	Edge
10	Ramp soak RUN/HOLD	Switches between ramp soak RUN/HOLD.	RUN	HOLD	Edge
11	No function	Not for use.		_	
12	Unlatch (all)	Cancels all the alarm latches.	Unlatch	_	Edge
13	Unlatch (alarm 1)	Unlatches the alarm 1.			
14	Unlatch (alarm 2)	Unlatches the alarm 2.			
15	Unlatch (alarm 3)	Unlatches the alarm 3.			
16	Unlatch (alarm 4)	Unlatches the alarm 4.			
17	Unlatch (alarm 5)	Unlatches the alarm 5.			
18	No function	Not for use.	_	—	—
19	Timer (alarm 1)	Runs the timer for the alarm 1.	Timer ON	Timer OFF	Level
20	Timer (alarm 2)	Runs the timer for the alarm 2.			
21	Timer (alarm 3)	Runs the timer for the alarm 3.			
22	Timer (alarm 4)	Runs the timer for the alarm 4.			
23	Timer (alarm 5)	Runs the timer for the alarm 5.			
24	No function	Not for use.	_	_	_
25	SV No. + 1	Increases the SV number by 1.	+1	_	Level
26	SV No. + 2	Increases the SV number by 2.	+2	_	Level
27	SV No. + 4	Increases the SV number by 4.	+4	-	Level
28	PID No. + 1	Increases the PID number by 1.	+1	-	Level
29	PID No. + 2	Increases the PID number by 2.	+2	_	Level
30	PID No. + 4	Increases the PID number by 4.	+4	_	Level
31	SV No. + 1,	Increases both the SV number and PID number by 1.	+1	_	Level
	PID No. + 1				
32	SV No. + 2, PID No. + 2	Increases both the SV number and PID number by 2.	+2	_	Level
33	SV No. + 4, PID No. + 4	Increases both the SV number and PID number by 4.	+4	-	Level
34	Ramp soak OFF	Stops ramp soak operation.	OFF	_	Edge
35	Ramp soak RUN	Runs ramp soak.	RUN	_	Edge
36	Ramp soak HOLD	Holds ramp soak	HOLD	_	Edge
37	Pattern No. + 1	Increases the pattern number by 1	+1	_	Level
38	Pattern No. + 2	Increases the pattern number by 2	+2	_	Level
30	Pattern No. + 4	Increases the pattern number by 4	+4	_	Level
40	Pattern No. + 8	Increases the pattern number by 8	+8		Level
40		Starte DL ooff start	Start		Edge
42	No function	Not for use	Jan		Lage
42	Delay start (alarm 1)	Enables delay start with the delay time = dLV1	- Dolou etc		
43	Delay start (alarm 2)	Enables delay start with the delay time = dLT I.	Delay Sta		
44	Delay statt (alarm 2)	Enables delay start with the delay time = 0LY2.	Delay sta		_
45		Enables delay start with the delay time = dLY3.	Delay sta	antenable	
46	Delay start (alarm 4)	Enables delay start with the delay time = dLY4.	Delay sta	art enable	
47	Delay start (alarm 5)	Enables delay start with the delay time = dLY5.	Delay sta	art enable	
48	No function	Not for use.	—	—	—

15-1. PXF5 & PXF9 (Standard type)

			4	5	6	7	8		91	0 1	1 12	2 13
		PXF		A			2]-[0	0
			.									
Digit	Specifications	Note										
4	<front h="" panel="" size="" w="" ×=""></front>		₩									
	48 × 96 mm		5									
	96 × 96 mm		9	+								
5	-			Α								
6	<control 1="" output=""></control>				₩							
	Relay contact (SPST)				А							
	Relay contact (SPDT)				В							
	SSR drive output				С							
	Current output		[Ē	-			1			
	Voltage output				Ρ							
7	<control 2="" output=""></control>					┥	,					
	None					Ý						
	Relay contact (SPST)					А						
	SSR drive output					С						
	Current output					F	- 1		1			- 1 -
	Voltage output					P						
	Transfer output (current)					R						
	Transfer output (voltage)					S		,				
8	<revision code=""></revision>						2		1			+
9	<alarm output=""></alarm>								•			+
Ŭ	None								Ó			
	1 point								1			
	2 points								F			
	3 noints								M -			· - † -
	2 points (independent common)								J			
10	2 points (independent contract) <power instruction="" manual="" supply="" voltage=""></power>								<u> </u>			+
	100 to 240 V AC, Japanese & English								,	v I		
	100 to 240 V AC. English								١			
	100 to 240 V/AC Chinese & English								N	v //		
	$24 \vee \Lambda C/DC$ Japanese & English									<u>_</u>		· - -
	24 V AC/DC, Sapanese & English								/ [
	24 V AC/DC, Chinese & English								r I			
11			⊢							<u> </u>	_	+
	INUNE DS 495 Communication									۲ ۸		
	RS-405 COMMUNICATION									א ר		
	Digital iliput (DIT, DIZ) Pomoto SV input + Digital input (DI2)	Noto2								,	,	
	CT input - Digital input (DI3)	Note1									! -	· - -
	CT IIIput + Digital IIiput (DIT)	INDIG								(,	
	RS-465 communication + Digital Input (DI1)									1		
	κ_{0} -465 communication + Digital input (DI3, 4, 5)									C	,	
40	+ Auxiliary alarm output (AL4, AL5)		\vdash									+
12	-										×	•
13											0	0

Note 1: When using the CT input as a heater burnout alarm, add one alarm output for it. (Add one point in the 9th code.) Note 2: When a current input is used, a resistance of 250Ω is required at the input terminal.

		PXF	4	5 A	6 ·	7 8 Y 2	8 2 -	9	<u>10 1</u>	1 12 0	2 13) 0
Diait	Specifications	Note	1								
4	<pre><front h="" panel="" size="" w="" ×=""></front></pre>		i↓								
·	48 × 96 mm		5								
	96 × 96 mm		9	Ļ							
5	-			Ă					1		\square
6	<control 1="" output=""></control>			,							
	Motorized valve control output (without PFB input)			Ś	Ŝ						
	Motorized valve control output (with PFB input)			١	V						
7	<control 2="" output=""></control>										
	None				`	Y					
8	<revision code=""></revision>					1	2				
9	<alarm output=""></alarm>							+			
	None							0			
	1 point							1			
	2 points							F	_		
	3 points		[M			
	2 points (independent common)							J			
10	<power instruction="" manual="" supply="" voltage=""></power>								♦		
	100 to 240 V AC, Japanese & English								Y		
	100 to 240 V AC, English								V		
	100 to 240 V AC, Chinese & English								W		
	24 V AC/DC, Japanese & English								А		
	24 V AC/DC, English								В		
	24 V AC/DC, Chinese & English								D		
11	<option></option>										
	None								١	r	
	RS-485 communication + Digital input (DI1, 2, 3)								ι	J	
12	-									-	r 🔶
13										0) ()

16. Specifications

Power supply voltage	100 (-15%) to 240 (+10%) V AC, 50/60Hz, 24 (±10%) V DC/AC, 50/60Hz
Power consumption	13 VA MAX. (100 to 240 V AC), 8 VA MAX. (24 V DC/AC)
Control output	Relay contact output
	1 SPST contact, 250 V AC/30 V DC, 3 A (resistive load)
	1 SPDT contact, 250 V AC/30 V DC, 5 A (resistive load)
	SSR/SSC drive output (voltage pulse output)
	ON voltage: 12 V DC (10.7 to 13.2 V DC)
	OFF voltage: 0.5 V DC or lower
	Maximum current: 20 mA DC
	Load resistance: 600 Ω MIN.
	Current output
	0 to 20 mA DC/4 to 20 mA DC
	Accuracy: ±5%FS
	Load resistance: 500 Ω MAX.
	Voltage output
	0 to 5 V DC/1 to 5 V DC/0 to 10 V DC/2 to 10 V DC
	Accuracy: ±5%FS
	Load resistance: 10 kΩ MIN.
Process value input	Accuracy
	Thermocouple input: either ±1°C ±1 digit or ±0.3% of indicated value ±1 digit. whichever is larger
	*except: Thermocouple B: 0°C to 400°C: no accuracy assurance
	Thermocouple R: 0°C to 500°C: ±3°C ±1 digit Other thermocouples: -200°C to -100°C: ±2°C ±1 digit
	RTD input: ±0.8°C ±1 digit or ±0.2% of indicated value ±1 digit, whichever
	is larger
	mV input, voltage input, current input: ±0.3%FS ±1 digit
Alarm output	Relay contact output (AL1 to AL5)
	1 SPST contact, 250 V AC/30 V DC, 1 A (resistive load)
Digital input	Number of inputs: 3
	Contact capacity: 5 V DC, 2 mA (per point)
	Input pulse width: 50 ms MIN.
	ON judgment: 2 V DC or lower
	OFF judgment: 3 V DC or higher
Transfer output	0 to 20 mA DC/4 to 20 mA DC 0 to 5 V DC/1 to 5 V DC/ 0 to 10 V DC/2 to 10 V DC)
	Transfer data: PV, SV, DV, MV
	Accuracy: ±0.2%FS (±5%FS current output for 1 mA or lower)
	Load resistance: 500 Ω MAX. (current), 10 kΩ MIN. (voltage)
Remote SV input	0 to 5 V DC/1 to 5 V DC/0 to 10 V DC/2 to 10 V DC
	0 to 20 mA DC/4 to 20 mA DC (an external resistance of 250 Ω is required
Current transformer (CT) input	Single phase current transformer: 1 point for 1 to 30 A/20 to 100 A
	Besistance range: 100 to 2 5k0 (three line ture)
input	Resolution: 0.5% ES
	Insuit accuracy: +1.0% ES
	Corresponding full stroke time: 30 sec to 180 sec
Valve position feedback input	SPST contact x 2 (without interlock circuit) 250 V AC(30 V DC 3 A (resistive
(Potentiometer)	load)
Communication	RS-485 interface
	Communication method: Half-duplex bit serial, asynchronous communication
	Transmission rate: 9600 bps, 19200 bps, 38400 bps, 115400 bps
	Protocol: Modbus RTU compatible
	Transmission distance: Up to 500 m (total connection length)
	Connectable units: 31 units MAX.
Loader interface	TTL Level
	Connection method: dedicated cable
	Communication method: Half-duplex bit serial, asynchronous communication
	Transmission rate: 38400 bps, no parity
	Protocol: Modbus RTU compatible
Storage temperature and humidity	-20°C to 60°C, 90%RH or less (no condensation)
Operating temperature and humidity	-10°C to 50°C, 90%RH or less (no condensation)
Altitude	up to 2000 m
Reeommemd fuse	250V AC, 0.1A T (Time-Lag) for 100 to 240V AC Power supply, 400V DC/400V AC, 1A T (Time-Lag) for 24V DC/24V AC Power supply
Service life	10 years (under an average ambient temperature of 25°C) The life is shortened by half when the temperature rises by 10°C (Arrhenius' law). If you use the controller inside a cabinet or the like, please note that the ambient temperature can rise.

17. Limited warranty

1. Scope of warranty

If malfunction occurs in the period of warranty due to Fuji Electric, the malfunctioning parts are exchanged or repaired for free.

However, in the case where an engineer needs to visit your place for replacement or repair, you will be charged our call out fee.

Please note that we cannot provide commissioning and/or readjustment for whole system including our product at repair or replacement of failed parts.

The warranty does not apply to the following cases

- The malfunction occurs due to inappropriate conditions, environment, handling or usage that is not instructed in a catalog, instruction book or user's manual.
 The malfunction is caused by the factors that do not originate in the purchased or delivered
- (2) The maturation is caused by the factors that do not originate in the proclased of derivered product.
 (3) The maturation is caused by other devices or software design that does not originate in Fuil

 (3) The manufaction is caused by other devices or software design that does not originate in Fuji Electric products.
 (4) The maifunction occurs due to an alteration or repair that is not performed by Fuji Electric.

- (4) The maintain occurs due to an alteration of repair that is not performed by Fuji Electric.
 (5) The malfunction occurs because the expendable parts listed in an instruction book or connectable were not maintained nor exchanged in an appropriate manner.
- (6) The malfunction occurs due to factors that were not foreseeable by the practical application of science and technology at the time of purchase or delivery.

science and technology at the time of purchase or delivery.
(7) The malfunction occurs because the product is used for an unintended purpose.
(8) The malfunction occurs due to a disaster or natural disaster that Fuji Electric is not responsible for.

2. Exclusion of liability for loss of opportunity

Regardless of the time period of the occurrence, the amount of compensation assumed by Fuji Electric for damage, excluding which is caused by intentional acts or acts of gross negligence or illegal act by Fuji Electric, shall not exceed the amount stipulated in the contract with the customer. Fuji Electric is not liable for the damage to products that were not manufactured by Fuji Electric, incidental damages or consequential damages, or damage caused due to special situations regardless of whether it was foreseeable or not, or passive damages such as opportunity loss or lost profits of the purchaser.

3. Scope of application

- This equipment must be used under the following conditions:
- The use of the equipment incurs no risk of a serious accident even if a failure or malfunction
 occurs on the equipment, and in case of product failure or malfunction, safety measures such as
 redundant design, prevention of malfunction, fail safe setting, foolproof mechanism are provided
 outside of the equipment by the user.
- The product described in this document is designed and manufactured as a general-purpose products for general industrial applications.
- The warranty does not apply to the following cases:
- For the use not described in or beyond the conditions or environment specified in the instruction manual or the user manual,
- For the use which has large influence on publicity including nuclear power and other power generation, gas, and/or water,
- For the use in which safety is especially required, because it may seriously affect railroads, vehicles, combustion equipment, medical equipment, entertainment devices, safety equipment, defense equipment, and/or human lives and property.

However, we will study the possibility of application of the equipment for the above use, if the user limits the usage of it and agrees to require no special quality. Please consult us.