

# **New-Generation PXF Series**

# **Digital Temperature Controller**

# Exceeding Your Expectations...

- ▼ High Speed and High Accuracy
- ▼ Multi-Drop Master Function
- ▼ Universal Input



# Superior Versatility and Flexibility for a Wide Range of Applications



# Multi-Functional to Suit Your Needs

In addition to 9 types of temperature control functions including on-off control, heating/cooling control, and 2-degrees-of-freedom PID, useful functions such as multi-drop control using RS-485 network and simple watt-hour monitoring are available. All these features make PXF practical for any applications.

\*For details of each functions, see pages 4-7.

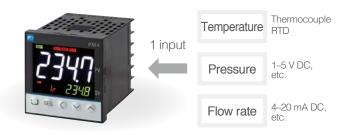


# RS-485 Communication (option)

SV can be transmitted to multi-PXFs through communication. Synchronous temperature-rise control is available in combination with 2-degrees-of-freedom PID.



# **Universal Input**



Easy switchover by parameter setting

# Tallest PV Characters in the Industry

Bright and clear white PV display for optimal viewing



# **Compact Design**

With only 58-mm depth, compact enough to be installed on small equipment



# Size Selection

3 different sizes, with a depth of 58 mm



# Parameter Setting Available on PC

Parameter loader software is download free from our website. Optional USB cable enables PXF to be connected to and powered from PC.



# **Advanced Control Functions**

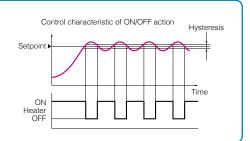
Parameter setting is available using the front keys or a PC with Fuji Electric's loader software.

# Standard Functions

# On/off Control

# **Simple and Basic Control**

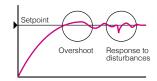
When process value (PV) is below the set value (SV), PXF turns on the output to energize the heater, and vice versa. In this way, PXF keeps the temperature constant by turning the output on and off based on the SV as a threshold.



# PID Control with Auto Tuning

# **Typical Control Based on PID Theory**

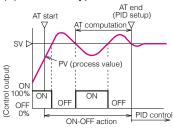
\* Overshoot may occur due to external disturbance.



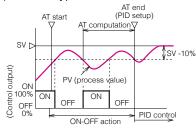
# PID Auto Tuning

The controller calculates optimal PID parameters. PXF has 2 types of auto-tuning functions; the standard type (auto-tuning with SV used as reference) and the low SV type (auto-tuning with the value 10% below SV used as reference).

(a) Standard type AT start

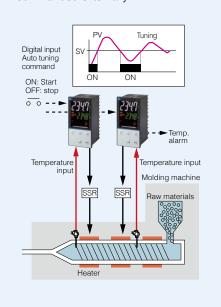


(b) Low-PV type



**Molding Machine** 

Start/stop of auto tuning can be commanded externally.

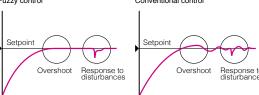


# Fuzzy Control with Auto Tuning

# **Suppresses Overshoot by Fuzzy Calculation**

By monitoring PV, PXF suppresses overshoot without lengthening startup time. At the same time, it can quickly deal with external disturbances.

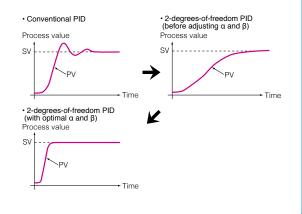
Fuzzy control



# 2-Degree-of-Freedom PID with Auto Tuning

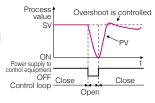
# **Combined Method for Stable Control**

Suppresses overshoot and undershoot occurs at startup or at SV change, or by external disturbances.



# Open-Loop Supported PID2 Control **Suppresses Overshoot**

Reduces overshoot in the processes where the controlled equipment is power cycled.

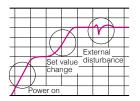


# Self Tuning Control

# **Auto-Tuned PID for Changing Temperature**

At power up, SV change, or during external disturbance, tuning is made automatically so that the PID parameters are re-optimized.

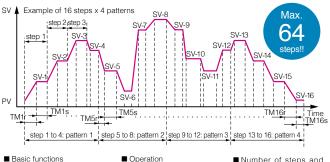
\*For some objects of control, PID values



# Simple Program Control (Ramp Soak Function)

# **Up to 64 Steps**

PXF automatically changes SV to the preset values at preset times. You can set up to 64 steps and 15 types of operation patterns. For example, when you bake four kinds of bread, you can divide 64 steps into four patterns to set suitable temperature for each bread.



- 1. [h·min] or [min·s]
  2. Guarantee soak
  3. Repeat action
  4. PV start

- 5. Delay start 6. Power restoring function

# You can start/stop/suspend

the operation using a user key, parameter setting, digital input, or communication.

# Number of steps and patterns Steps Patterns

# Controlling Temperature Gradient of Furnace

by heating patterns



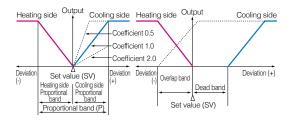
# Ramp Soak Function

Temperature rise/fall pattern is controlled by setting a heat pattern having a gradient. You can externally start or reset the pattern.



# **Optional Functions**

# Heating and Cooling Control with Dual Output

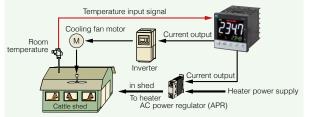


\* For the cooling side proportional band, set a coefficient with respect to the heating side proportional band. (Works as on-off control if coefficient is zero.)

# Energy Savings in Livestock Barns

Both heating and cooling are controlled with one temperature controller using its two control outputs.

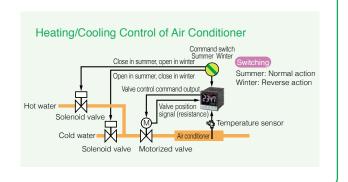
Power consumption can be curbed by controlling a cooling fan motor with inverter.



# Motorized Valve Control

# Valve Opening/Closing is Available

- · Position feedback control based on motorized valve position signal
- · Servo control without valve position signal



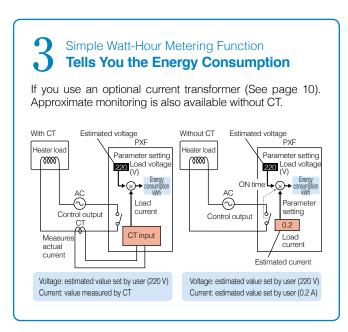
# Variety of Functions

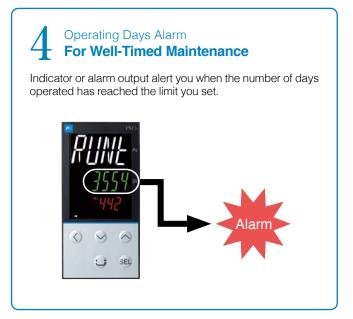
Expanding the Uses of Temperature Controllers and Improve the User Experience

# Standard Functions

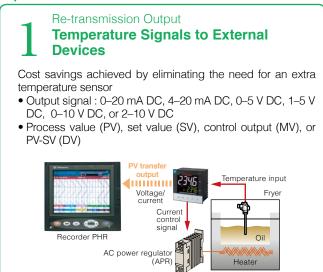
# 

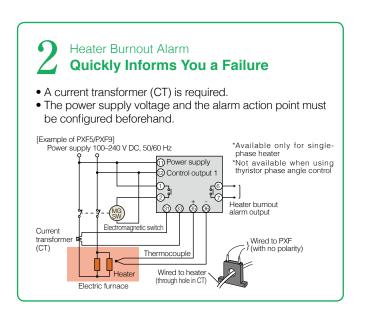
# Soft Start Saves Energy at Startup Prevents the output being maximum when turning on the equipment (including the temperature controller). This is useful for suppressing the load at equipment startup. Control output (MV) MV without soft start output set value NV without soft start (limited) Soft start set time Digital input ON





# **Optional Functions**





# Alarm Output Up to 5 Alarms (PXF4: up to 3)

	Alarm type	Action diagram
larm	Upper limit absolute value	→ PV
alue a	Lower limit absolute value	ALn PV
Absolute value alarm	Upper limit absolute value (with hold)	———— PV
Abso	Lower limit absolute value (with hold)	ALn PV
	Upper limit deviation	SV PV
Ę	Lower limit deviation	ALn: SV PV
on alar	Upper and lower limits deviation	ALn ALn SV PV
Deviation alarm	Upper limit deviation (with hold)	SV PV
Δ	Lower limit deviation (with hold)	ALn : SV PV
	Upper and lower limits deviation (with hold)	ALn ALn SV PV
	Range upper and lower limits deviation (ALM1/2 independent operation)	ALn ALn PV
Ę	Range upper and lower limits absolute value	AL2 AL1 → PV
Range alarm	Range upper and lower limits deviation	AL2 AL1 SV PV
Ra	Range upper limit absolute value and lower limit deviation	SV AL1 PV
	Range upper limit deviation and lower limit absolute value	AL2 SV PV

# Digital Input SV Can be Switched Externally SV change, AT start, timer startup, program selection, start/ stop/reset, PID changeover, etc. Changeover of 4 set values (front SV, SV1, SV2, SV3) can be commanded externally. Digital input SV change command SSR drive output SSR drive input Temperature input



# 6

# **RS-485 Communication**

User address mapping function
 Users can create a list of necessary parameters (max. 32 words) for quick data acquisition on that data set.
 Communication speed: max. 115.2 kbps

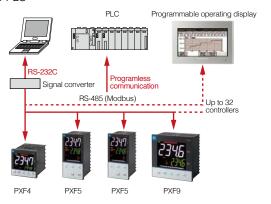
Address	Parameter		
30001	PV	Max.3	32 words
30002	SV(Read)	Address	Parameter
30003	DV	30001	PV
30004	MV1	30002	SV(Read)
		40003	SV(Write)
:	:	30004	MV1
40003	SV(Write)	40006	Р
40004	STBY	40007	1
40005	AT	40008	D
40006	Р		•
40007	1	:	:
40008	D	-	-
		-	-
:	:	-	-

Multidrop master function
 Synchropous temperature rise of

Synchronous temperature-rise control is available in combination with 2-degrees-of-freedom PID.



- Parameter copy function
   Parameter values can be copied to multiple PXFs simultaneously.
- Communication with PC, programmable operation display, or PLC



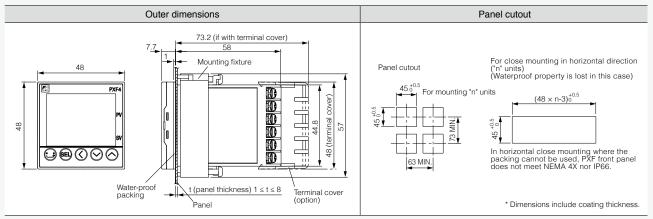
# **Product Lineup**

Model			PXF4	PXF5	PXF9	
Appearance		2340	2349 = 2349 = 1e	2346 N 12346 SV		
Front panel	size (W x H)		48 × 48 mm	48 × 96 mm	96 × 96 mm	
Depth				58 mm	<u> </u>	
Display digit	S			4-digit (PV and SV)		
Character he	eight (PV)		15.3 mm	18.1 mm	26 mm	
Indication ac	ccuracy		RTD input: ±0.2% of indication Thermocouple input: ±0.3%± Voltage input and current inpu	1 digit of indicated value or ±1		
Sampling rate	te			50 ms		
		Process value input	Universal ir	nput (RTD, thermocouple, volta	age/current)	
		Remote SV input		Voltage/current		
Input signal		Current transformer (CT) input		Dedicated CT (1 to 100 A)		
input signai	Option	Motorized valve position input	-	100Ω to 2.8	5kΩ (3-wire)	
		Digital input (DI)	1 (Motorized valve control version: up to 3)	Up	to 3	
		Relay contact		•		
	Control out-	SSR/SSC drive output		•		
	put	Current output (linear)		•		
		Voltage output (linear)		•		
Output		Motorized valve control output		•		
signal		Analog re-transmission output (voltage)		•		
	Onting	Analog re-transmission output (current)		•		
	Option	Heater burnout alarm output		•		
		Operating days alarm		•		
		Alarm/event contact output (DO)	Up to 3	Up	to 5	
		ON/OFF control		•		
		PID control*		•		
		Fuzzy control*		•		
Control meth	nod	2-degrees-of-freedom PID control*		•		
(*with auto to		Open-loop supported PID2 control		•		
		Self tuning		•		
		Ramp soak function (simple program control)		Up to 64 steps		
	Option	Heating/cooling control*		•		
	Ориоп	Motorized valve control		•		
		Number of PV/PID patterns		Up to 8		
		SV/PID switchover		•		
		Soft start		•		
Functions		Simple watt-hour metering		•		
Operating days  Manual operation  User key		Operating days		•		
		Manual operation		•		
		•				
Communi-		Loader interface		•		
cation	Option	RS-485 (Modbus)		•		
Power sup-		100-240 V AC, 50/60 Hz		•		
ply voltage Option 24 V DC/AC			•			
Power consumption		10 VA MAX.	13 VA MAX.	13 VA MAX.		
Screw termin	nals			M3		

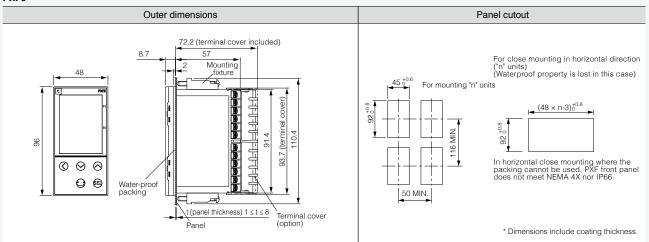
<sup>\*</sup>Some functions are unavailable depending on the model. For more detail, please refer to the specifications on Page 14.

# **Outline Diagram**

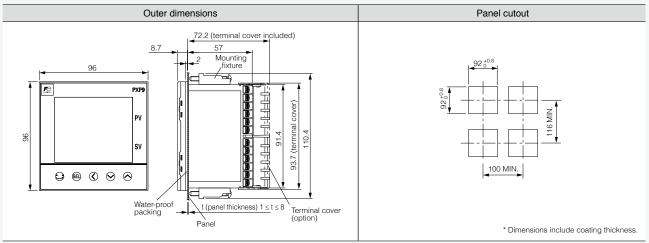
## PXF4



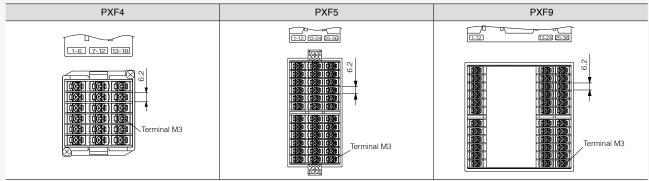
# PXF5



# PXF9



# Rear view



# **Ordering Code**

# **PXF4 Standard Type**

Digit	Specifications	Code
4.4	Front panel size W x H	
1-4	48 × 48mm	PXF4
5	-	А
	Control output 1	
	Relay contact (SPST) *1	А
6	Relay contact (SPDT) *1	В
ъ	SSR drive output	С
	Current output	E
	Voltage output	Р
	Control output 2	•
	None	Υ
	Relay contact (SPST)	Α
_	SSR drive output	С
7	Current output	Е
	Voltage output	Р
	Re-transmission output (current)	R
	Re-transmission output (voltage)	S
8	Revision code	2
	Alarm output	
	None	0
_	1 point	1
9	2 points	F
	3 points	М
	2 points (independent common)	J
	Power supply voltage/instruction manual	
	100 to 240 V AC, Japanese & English	Υ
	100 to 240 V AC, English	v
10	100 to 240 V AC, Chinese & English	W
	24 V AC/DC, Japanese & English	Α
	24 V AC/DC, English	В
	24 V AC/DC, Chinese & English	D
	Option	
	None	Y
	RS-485 Communication	M
11	Digital input (DI1)	S
	RS-485 communication + Digital input (DI1)	······································
	RS-485 communication + Remote SV input *2	K
	RS-485 Communication + CT input *3	J
12	no recommendation remput	1
13	_	00

\*1: Not available for the 7th code "C", "E", "P", "R", "S". However, if you want to order the 6th code "A" (SPST relay contact for the control output 1) and the 7th code "R" or "S" (current/ voltage re-transmission output for the control output 2), specify the model as follows:

PXF4AA \$\frac{\text{S}}{2} \cdot 2 \cd

- \*2: When using current for the remote SV input, add a 250-ohm resistor to the input terminal.
  \*3: When using the CT input for heater burnout alarm, add one alarm output for it in the 9th

# PXF5 & PXF9 Standard Type

Digit	Specification	Code
	Front panel size W x H	
1-4	48 × 96 mm	PXF5
	96 × 96 mm	PXF9
5	_	Α
	Control output 1	
	Relay contact (SPST)	Α
6	Relay contact (SPDT)	В
ь	SSR drive output	С
	Current output	Е
	Voltage output	Р
	Control output 2	
	None	Υ
	Relay contact (SPST)	Α
7	SSR drive output	С
7	Current output	Е
	Voltage output	Р
	Re-transmission output (current)	R
	Re-transmission output (voltage)	S
8	Revision code	2
	Alarm output	
	None	0
9	1 point	1
9	2 points	F
	3 points	M
	2 points (independent common)	J
	Power supply voltage/instruction manual	
	100 to 240 V AC, Japanese & English	Υ
	100 to 240 V AC, English	V
10	100 to 240 V AC, Chinese & English	W
	24 V AC/DC, Japanese & English	А
	24 V AC/DC, English	В
	24 V AC/DC, Chinese & English	D
	Option	
	None	Υ
	RS-485 Communication	M
11	Digital input (DI 1 and DI2)	T
"	Remote SV input + Digital input (DI3) *1	Н
	CT input + Digital input (DI1) *2	G
	RS-485 communication + Digital input (DI1)	V
	RS-485 + Digital input (DI3, DI4, DI5) + Auxiliary alarm output (AL4, AL5)	С
12		00
13	_	00

- 1: When using current for the remote SV input, add a 250-ohm resistor to the input terminal
- $^{\star}2:$  When using the CT input for heater burnout alarm, add one alarm output for it in the 9th  $^{\cdot}$

# **PXF4 Motorized Valve Control Type**

Digit	Specifications	Code	
	Front panel size W x H		
1-4	48 × 48mm	PXF4	
5	1	А	
6	Control output 1		
ь	Motorized valve control output (without PFB input)	Ţ	
7	Control output 2		
,	None	Υ	
8	Revision code	2	
	Alarm output		
	None	0	
9	1 point	1	
	2 points	F	
	2 points (independent common)	J	
	Power supply voltage/instruction manual		
	100 to 240 V AC, Japanese & English	Y	
	100 to 240 V AC, English	V	
10	100 to 240 V AC, Chinese & English	W	
	24 V AC/DC, Japanese & English	А	
	24 V AC/DC, English	В	
	24 V AC/DC, Chinese & English	D	
	Option		
11	None	Y	
- 11	Digital input (DI 1, 2, 3)	D	
	RS-485 communication + Digital input (DI1)	V	
12		00	
13		00	

# Optional items

Name	Model	
Current transformer	1 A to 30A	ZOZ*CCTL-6-S-H
Current transformer	20 to 100A	ZOZ*CCTL-12-S36-8
Terminal cover	ZZPPXR1-A230	
Parameter loader interface cable	ZZP*TQ501923C3	
Shunt resistor (250 Ω±0.1%)	ZZPPXR1-A190	
Panel mounting adapter for replacement from	ZZP*TQ502732C1	

# PXF5 & PXF9 Motorized Valve Control Type

Digit	Specifications	Code
	Front panel size W x H	
1-4	48 × 96 mm	PXF5
	96 × 96 mm	PXF9
5		Α
	Control output 1	
6	Motorized valve control output (without PFB input)	S
	Motorized valve control output (with PFB input)	V
7	Control output 2	
•	None	Υ
- 8	Revision code	2
	Alarm output	
	None	0
9	1 point	1
J	2 points	F
	3 points	M
	2 points (independent common)	J
	Power supply voltage/instruction manual	
	100 to 240 V AC, Japanese & English	Υ
	100 to 240 V AC, English	V
10	100 to 240 V AC, Chinese & English	W
	24 V AC/DC, Japanese & English	Α
	24 V AC/DC, English	В
	24 V AC/DC, Chinese & English	D
	Option	
11	None	Υ
	RS-485 communication + Digital input (DI1, DI2, DI3)	U
12	_	00
13		

# **Optional items**

Name		Model
Current transformer	1 A to 30A	ZOZ*CCTL-6-S-H
Current transformer	20 to 100A	ZOZ*CCTL-12-S36-8
Terminal cover *1		ZZPPXF1-B100
Parameter loader interface cable		ZZP*TQ501923C3
Shunt resistor (250 Ω±0.1%)		ZZPPXR1-A190

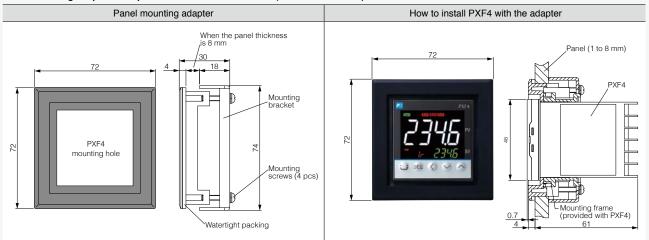
<sup>\*1:</sup> For PXF9, two covers are necessary for one unit.

# Scope of delivery

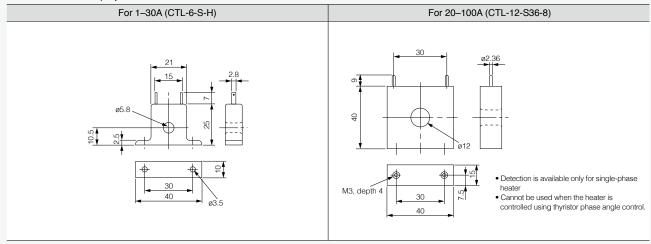
- $\cdot \ \text{Controller} \times 1$
- · Instruction manual  $\times$  1
- · Panel mounting adapter  $\times$  1 set
- · Water-proof packing × 1

# **Outline Diagram of Optional Items**

Panel mounting adapter for replacement from PXR7 to PXF4 (ZZP\*TQ502732C1)



# Current transformer (CT)



# **Insulation Block Diagram**

# PXF4

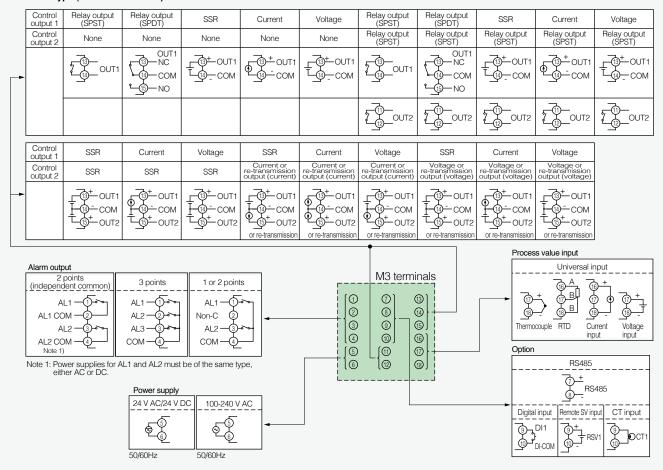
Power	supply	Internal circuit	
Control output 1 (relay contact) or Motorized valve OPEN output		Process value input Remote SV input CT input	
Control output 2 (relay contact) or Motorized valve CLOSE output		Control output 1 (SSR drive, current, voltage)  Control output 2 (SSR drive, current, voltage)	
Alarm output 1 (Relay contact)	Alarm output 1 to 3	Digital input 1 to 3	
Alarm output 2 (Relay contact)	(Relay contact)	Communication (RS-485)	
When the 9th code is "J" When the 9th co is other than "J (AL1 and AL2: independent common) (AL1, AL2, and A shared common)		Basic insulation Functional insulation No insulation	

# PXF5 and PXF9

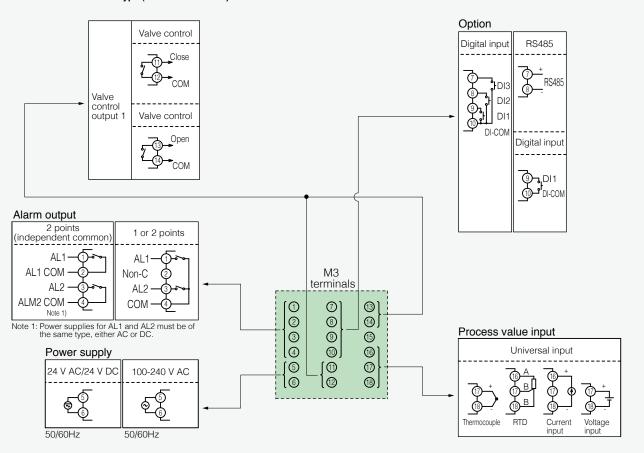
Powe	r supply	Internal circuit	
Control output 1 (relay contact) or Motorized valve OPEN output		Process value input Remote SV input Current transformer (CT) input	
Control output 2 (relay contact) or Motorized valve CLOSE output		Valve position feedback (PFB) input  Control output 1  (SSR drive, current, voltage)	
Alarm output 4 and 5 (relay contact)		Control output 2 (SSR drive, current, voltage) or re-transmission output	
Alarm output 1 (Relay contact)	Alarm output 1 to 3	Digital input 1 to 3	
Alarm output 2 (Relay contact) (Relay contact)		Communication (RS-485)	
When the 9th code is "J" When the 9th code is other than "J" (AL1 and AL2: independent common) (AL1, AL2, and AL3: shared common)		Basic insulation Functional insulation No insulation	

# **Connection Diagram**

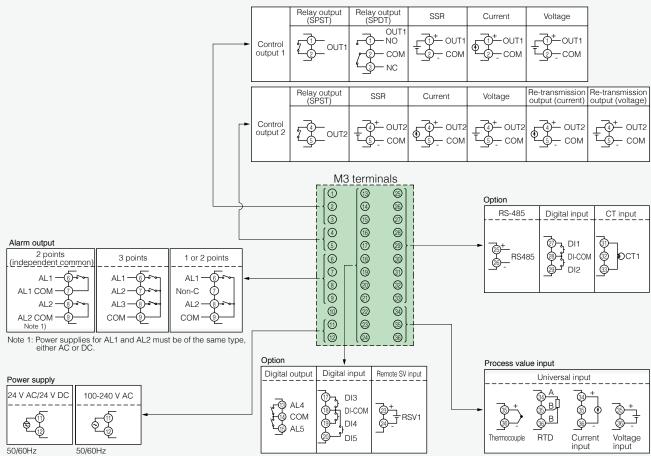
# Standard type (base model: PXF4)



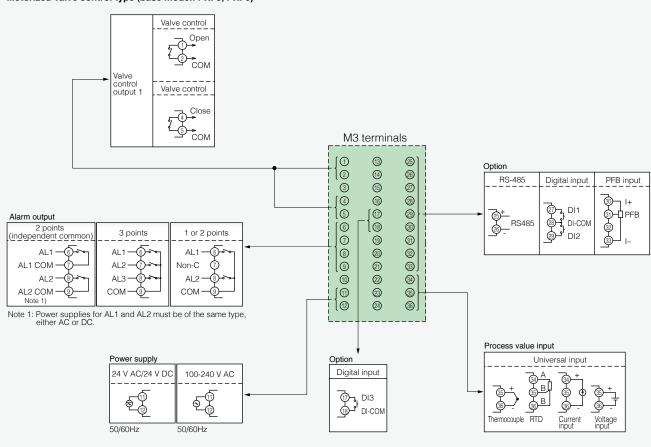
# Motorized valve control type (base model: PXF4)



# Standard type (base model: PXF5, PXF9)



# Motorized valve control type (base model: PXF5, PXF9)



# **Specifications**

# General specifications

Power supply voltage	100 V (-15%) to 240 V (+10%) AC, 50/60 Hz, 24 V AC/DC (±10%)			
	Model	100 to 240 V AC	24 V DC/AC	
Power consumption	PXF4	10 VA MAX.	5 VA MAX.	
	PXF5 & PXF9	13 VA MAX.	8 VA MAX.	
Insulation resistance	20 MΩ or more (at 500 V DC)			
Withstand voltage	Power source ↔ all terminals: 1500 V AC for 1 min Relay contact output ↔ all terminals: 1500 V AC for 1 min Between others: 500 V AC for 1 min			

## Process value input

Process value in	Process value input		
Number of inputs	1		
Input setting	Programmable scale		
Input signal	See Table 1 on Page 15. (Universal input: thermocouple/RTD/voltage/current)		
Standard measurement range and input type	See Table 1 on Page 15.		
Indication accuracy (at Ta = 23°C)	Thermocouple input: either ±1°C ±1 digit or ±0.3% of indicated value ±1 digit, whichever is larger  *except: Thermocouple B: 0 to 400°C: no accuracy assurance Thermocouple R: 0 to 500°C: ±3°C ±1 digit Thermocouples of which measuring range is between -200°C and -100°C: ±2°C ±1 digit  RTD input: ±0.8°C ±1 digit or ±0.2% of indication value ±1 digit, whichever is larger  mV input, voltage input, current input: ±0.3%FS ±1 digit		
Temperature effect on sensitivity	±0.3%FS/10°C		
Indication resolution	See Table 1 on Page 15.		
Sampling rate	50 ms		
Input impedance	Thermocouple, mV input: 1 MΩ or more  Current input: 150 Ω or less (built-in diode)  Voltage input: About 1 MΩ		
Variation by signal source resistance	Thermocouple, mV input: ±0.3%FS ±1 digit per 100 Ω  Voltage input: ±0.3%FS ±1 digit per 500 Ω		
Allowable wiring resistance	• RTD: 10 Ω MAX. (per wire)		
Allowable input voltage:	DC voltage input: within ±35 V Current input: within ±25 mA Thermocouple, RTD, mV input: within ±5 V		
Noise reduction ratio	Normal mode: 40 dB (50/60 Hz) Common mode: 120 dB (50/60 Hz) Between input and power supply: ±1°C at 220 V AC, 50/60 Hz		
Input correction	(a) User adjustment: ±50%FS for each of zero and span point (b) Process value shift: ±10%FS (c) Input filter: 0.0 to 120.0 s (filter is off when set to 0.0) (d) Square root extraction: -0.1 to 105% (OFF if set to -0.1%)		
Overrange · underrange	Out of the range between -5% and 105% FS (accuracy is not assured between -5 and 0, and between 100 and 105%FS)  *except:  • Pt (-200°C to 850°C) input: • O to 10 V DC input: • Thermocouple E: Out of the range between -5 to 102% of FS		

# Remote SV input (option)

Number of inputs	1
Input signal	Voltage: 0 to 5 V DC/1 to 5 V DC/0 to 10 V DC Current: 0 to 20 mA DC/4 to 20 mA DC (an external resistance of 250 $\Omega$ is required for current input)
Input impedance	Approx. 1 MΩ
Sampling rate	50 ms
Sampling rate	1 50 His

# Current transformer (CT) input (option)

, , , , , ,	
Input type	Single phase CT, 1 point For 1 A to 30 A: CTL-6-S-H For 20 A to 100 A: CTL-12-S36-8
Range of detected current	1 A to 100A
Detected current accuracy	Setpoint ±5%FS
Detected current resolution	0.1A
ON time necessary for detection	300 ms MIN.

# Digital input (DI) (option)

Functions	Remote mode selection, SV changeover, control standby, AT startup, timer startup, alarm unlatch, program selection, start/stop/reset, PID switching (normal/reverse), etc.
Sampling pulse width	50 ms MIN.
Input judgment:	ON voltage: 2 V DC or lower OFF voltage: 3 V DC or higher
Contact capacity:	5 V DC, about 2 mA (per point)
Specifications	No-voltage contact or transistor input
No. of points	PXF4 standard version: 1 PXF4 motorized valve control version: 3
	PXF5 and PXF9: up to 3

# Valve position feedback signal (potentiometer) input (option)

•	, , , , , , , , , , , , , , , , , , ,
Model	PXF5 and PXF9 (not available for PXF4)
Resistance range	100Ω to 2.5kΩ, three-wire
Resolution	0.5% FS
Accuracy	±1.0%FS
Temperature effect on sensitivity	±0.5%FS/10°C
Burnout function	None

# Control output

Control output	
No. of points	Up to 2 (2 points: Heating/cooling control)
Type Select among 1 to 6	1. Relay contact output (SPST) Proportional cycle: 1 to 150 s Contact structure: 1 SPST contact "SPST: single pole single throw Contact capacity: 250 V AC/30 V DC, 3A (resistive load) Minimum ON/OFF current: 10 mA (5 V DC) Mechanical life: 20 million operations MIN. (100 operations/min) Electrical life: 100,000 operations MIN. (rated load) Relay contact output (SPDT) Proportional cycle: 1 to 150 s Contact structure: 1 SPDT contact "SPDT: single pole double t row Contact capacity: 250 V AC/30 V DC, 5A (resistive load) Mechanical life: 50 million operations MIN. (100 operations/min) Electrical life: 100,000 operations MIN. (rated load) SSR/SSC drive output Proportional cycle: 1 to 150 s ON voltage: 12 V DC (between 10.7 and 13.2 V DC) OFF voltage: 0.5 V DC or lower Maximum current: 20 mA DC Load resistance: 600 Ω MIN. Current output (0 to 20 mA DC/4 to 20 mA DC) Accuracy: ±5%FS Load resistance: 500 Ω MAX. Voltage output (0 to 5 V DC/1 to 5 V DC/0 to 10 V DC/2 to 10 V DC) Accuracy: ±5%FS Load resistance: 10 kΩ MIN. Motorized valve control output Contact structure: 2 SPST contacts without interlock circuit "SPST: Single Pole Single Throw Contact capacity: 250 V AC/30 V DC, 3A (resistive load) Minimum ON/OFF current: 100 mA (24 V DC) Mechanical life: 20 million operations MIN. (100 operations/min) Electrical life: 100,000 operations MIN. (100 operations/min)

# Alarm output (DO) (option)

Number of outputs	Relay contact Shared COM: PXF5 & PXF9: ≤5, PXF4: ≤3 Independent COM: PXF5 & PXF9: ≤3, PXF4: ≤2
Output specifications	Relay contact output  Contact structure: SPST *SPST: single pole single throw Contact capacity: 250 V AC/30 V DC, 1A (resistive load) Minimum ON/OFF current: 10 mA (5 V DC) Mechanical life: 20 million operations MIN. (100 operations/min) Electrical life: 100,000 operations MIN. (rated load)
Output functions	Alarm output (see "Alarm function"), main unit control mode output, program status output, control output 1 and 2, etc.
Output cycle	100 ms

# Re-transmission output (option)

No. of points	1
Туре	Current/voltage output (0 to 20 mA DC/4 to 20 mA DC/0 to 5 V DC/1 to 5 V DC/0 to 10 V DC/2 to 10 V DC)  • Guaranteed output range: 0 to 21 mA DC/0 to 10.5 V DC  • Accuracy: ±0.2%FS (±5%FS at 1 mA or smaller)  • Resolution: 10,000 MIN.  • Load resistance: 500 Ω MAX. (current), 10 kΩ MIN. (voltage)
Output cycle	100 ms
Output contents	PV, SV, DV, MV
Additional function	Scaling function

# Display and keys

Туре	LCD (with backlight)
Indication contents	Process value indication: 11-segment, 4-digit [white] Setpoint indication: 11-segment, 4-digit [green] Screen No, indication: 7-segment, 4-digit [orange] Status indication: 42 indicator lamps
Luminance setting	possible (4 steps)
Keys	Sheet type keys (with emboss), 5 keys

# **Control functions**

ON/OFF control	Refer to page 4.
PID control	Dual control (heating/cooling)     PID parameters determination: Auto tuning
Fuzzy PID control	Dual control (heating/cooling)     PID parameters determination: Auto tuning
Self tuning control	Refer to page 5.
PID2 control	Dual control (heating/cooling)     PID parameters determination: Auto tuning
2-degrees-of-freedom PID	PID parameters determination: Auto tuning
Position proportional PID (servo) with position feedback	Full stroke time: 30 seconds MIN. (not available for PXF4)

# **Control parameters**

Proportional band (P)	0.1% to 999.9%
Integration time (I)	0 to 3200 s (invalidated when I = 0)
Differential time (D)	0.0 to 999.9 s (invalidated when D = 0)
Control cycle	100 to 900 ms (in 100 ms), 1 to 99 s (in seconds)
Anti-reset windup	0 to 100% of measurement range
Hysteresis band	50% of measurement range (at 2-position control only)
Number of SV and PID patterns	8: Changed by any of parameter setting, digital input, communication, user function keying, zone change.

# Control mode

Mode	Auto/Manual/Remote *During 2-position control in Manual mode, 2-position manual operation with MV = 100% or 0% is operated.
Mode changeover:	Auto ↔ Manual: Balanceless · bumpless     Auto/Manual→Remote: Balance · bumpless     Auto/Manual←Remote: Balance · bumpless

# Alarm

Number of alarm	Up to 5 (depends on the number of DO)				
Alarm type	Process value (upper limit/lower limit, absolute/deviation, range), main unit error, etc.(non-excitation, delay, latch, timer function option provided)				
Heater current alarm function (option)	Current transformer (CT) is to be prepared separately (see page 10				
Detectable range	1 A to 100 A				
Detected current resolution	0.1A				
Setting resolution	0.1A				
Hysteresis	0.0 to 100.0 A				

# RS-485 communication (option)

No. of points	1 point			
Physical specifications	s EIA-485			
Protocol	Modbus-RTU			
Communication method	Half-duplex bit serial, asynchronous communication			
Code type	Data length: 8 data bits. Parity: Odd, even, none.			
Baud rate	9600 bps, 19200 bps, 38.4 kbps, 115.2 kbps			
Connection	Up to 32 units			
Communication distance	ce Up to 500 m (total connection length)			
Additional function	Multidrop master function     The function in which slave devices can be operated by a master device by connecting several temperature controllers.     Programless communication     The function in which a temperature controller can be connected to a PLC without program.     Supported PLCs: Mitsubishi PLC Q series     Siemens PLC S7 series			

# Operation and storage conditions

Operating temperature	-10°C to 50°C			
Storage temperature	-20°C to 60°C			
Operating/storage humidity	90%RH or less (Non condensation)			
Warm-up time	30 min MIN.			
Vibration	during transportation: 9.8 m/s² (1 G) or less			
Impact	during transportation: 294m/s² (30 G) or less			

# Enclosure

Installation	Panel mount			
External terminals	Screw terminals, M3			
Case	Material: ABS, PPO     Non-combustibility grade: UL94V-0 equivalent     Color: Black			
Panel front side: IP66, NEMA-4X equivalent (When the mounted using our genuine packing. Not water-proof if closely together.)  Body: IP20 equivalent (slits on top and bottom)  Terminals: IP00 equivalent. Terminal cover can be mounted.				
Dimensions	Refer to page 9.			
Weight	PXF4: approx. 100 g, PXF5: approx. 170 g, PXF9: approx. 220 g			

# Customizable function and Program (ramp/soak) function

Number of program steps:	64 steps $\times$ 1 pattern, 32 steps $\times$ 2 patterns, 16 steps $\times$ 4 patterns, or 8 steps $\times$ 8 patterns (1 step = 2 segments)			
Control option Control by digital input Status output by digital output				
Basic functions	Segment time can be set in "Hour, Minutes" or "Minutes, Seconds"     Guarantee soak     Repeat action     Py start     Delay start     Power restoring function			
Memory backup	EEPROM			

# User key

Assignable functions	Auto/Manual change, Standby ON/OFF change, remote SV change,
	ramp/soak change, etc.

# Password function

3-level password

# Simple watt-hour metering function and operating days alarm

Simple watt-hour metering function	By connecting a current transformer (to be prepared separately), electric power consumption of the heater can be displayed. (Electric power is calculated based on the fixed voltage value you set.)     Current transformer (CT) is to be prepared separately (see page 10.)     Current detection range: 1 A to 100 A
Operating days alarm	<ul> <li>Indicates the number of days the controller has been operated and activates alarm output (optional) when it exceeds the setpoint.</li> <li>Useful for preventive maintenance because it let you know the ap- propriate time for maintenance work.</li> </ul>

# Data backup at power outage

on non-volatile memory

# Self-diagnosis

Program error supervision by watchdog timer

# Table 1 input type and range

Input type		Code (PvT)	Measurement range [°C]	Minimum input increment [°C]
	Pt 100	PT1	0.0 to 150.0	0.1
		PT2	0.0 to 300.0	0.1
		PT3	0.0 to 500.0	0.1
DTD		PT4	0.0 to 600.0	0.1
RTD		PT5	-50.0 to 100.0	0.1
		PT6	-100.0 to 200.0	0.1
		PT7	-199.9 to 600.0	0.1
		PT8	-200 to 850	1
DC voltage	0 to 5 V DC	0-5V	-1999 to 9999 (Range where scaling is al- lowed)	-
	1 to 5 V DC	1-5V		
	0 to 10V DC	0-10		
	2 to 10V DC	2-10		
	0 to 100mV DC	MV		
DC current	0 to 20 mA DC	0-20		
	4 to 20 mA DC	4-20		

T.		0 d (D T)	M	NE
Input type		Code (PvT)	Measurement range [°C]	Minimum input increment [°C]
		J1	0.0 to 400.0	0.1
	J	J2	-20.0 to 400.0	0.1
	J	J3	0.0 to 800.0	0.1
		J4	-100 to 1000	1
		K1	0 to 400	0.1
	к	K2	-20.0 to 500.0	0.1
	K	K3	0.0 to 800.0	0.1
		K4	-200 to 1300	1
	R	R	0 to 1700	1
	В	В	0 to 1800	1
Thermocou- ple	S	S	0 to 1700	1
	Т	T1	-199.9 to 200.0	0.1
		T2	-199.9 to 400.0	0.1
	E	E1	0.0 to 800.0	0.1
		E2	-150.0 to 800.0	0.1
		E3	-200 to 800	1
	L	L	-100 to 850	1
	U	U1	-199.9 to 400.0	0.1
		U2	-200 to 400	1
	N	N	-200 to 1300	1
	W	W	0 to 2300	1
	PL-II	PL-2	0 to 1300	1

Please read the following instructions carefully before operating the Digital Temperature Controller

# **▲WARNING**

# **Over-Temperature Protection**

Any control system design should take into account that any part of the system has the potential to fail.

For temperature control systems, continued heating should be considered the most dangerous condition, and the machine should be designed to automatically stop heating if unregulated due to the failure of the control unit or for any other reason.

The following are the most likely causes of unwanted continued heating:

- 1) Controller failure with heating output constantly on
- 2) Disengagement of the temperature sensor from the system
- 3) A short circuit in the thermocouple wiring
- 4) A valve or switch contact point outside the system is locked to keep the heat switched on.

In any application where physical injury or destruction of equipment might occur, we recommend the installation of independent safety equipment, with a separate temperature sensor, to disable the heating circuit in case of overheating.

The controller alarm signal is not designed to function as a protective measure in case of controller failure.



# ▲ Caution on Safety

\* Before using products in this catalog, be sure to read their instruction manuals in advance.



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